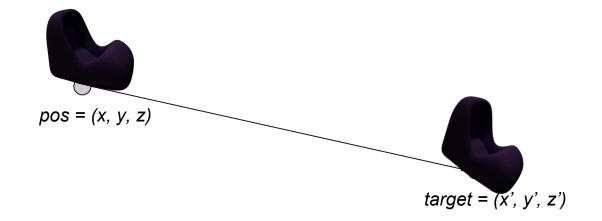
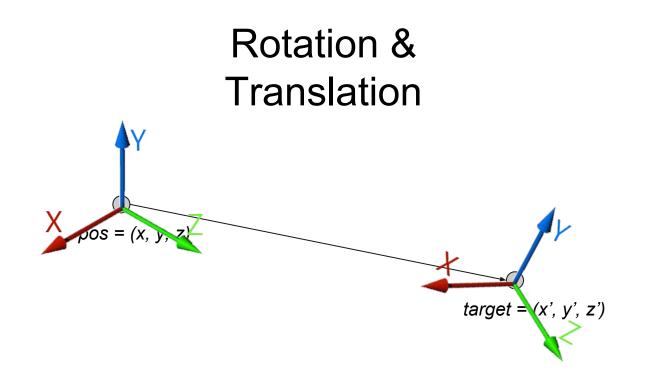
CSE 167 Discussion #8

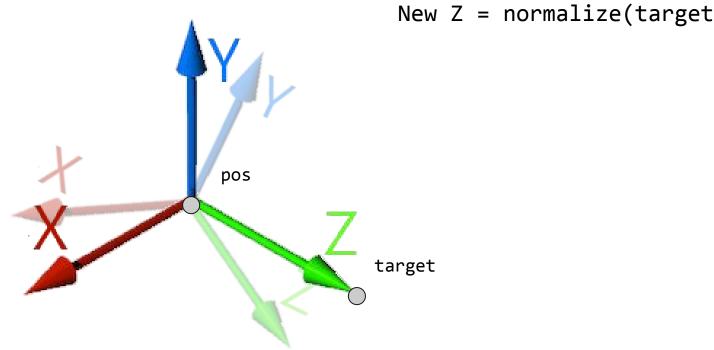
I'm the only human who can do it

Coaster Orientation

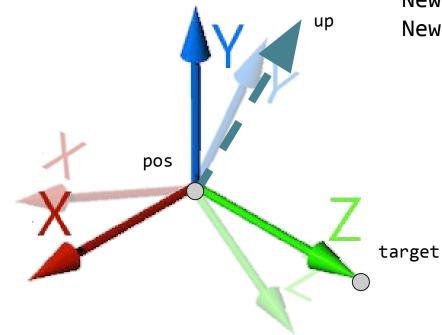


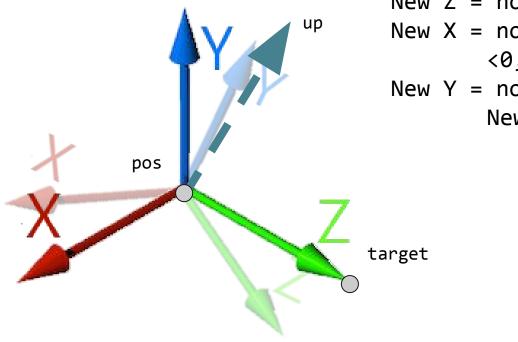
Coaster Orientation

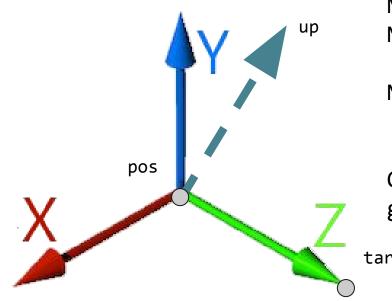




New Z = normalize(target - pos)







Construct the transformation matrix, given New (X, Y, Z) and pos

target

Moving Points

z-axis $z_{C} = \frac{e-d}{\|e-d\|}$

v avia	$\sim - up \times z_c$
x-axis	$\boldsymbol{x}_{C} = \frac{1}{\ \boldsymbol{u}\boldsymbol{p} \times \boldsymbol{z}_{C}\ }$

y-axis	$\mathbf{y}_{C} = \mathbf{z}_{C} \times \mathbf{x}_{C} = \frac{up}{\ up\ }$
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$$\boldsymbol{C} = \begin{bmatrix} \boldsymbol{x}_C & \boldsymbol{y}_C & \boldsymbol{z}_C & \boldsymbol{e} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Moving Points

 If we take our control point's position and add the camera's scaled x-axis and scaled y-axis, we can move the control point in the camera's x-y plane

 \circ control_pos = control_pos + s_{x-axis} * x-axis + s_{y-axis} * y-axis