CSE 167: Introduction to Computer Graphics Lecture #10: Advanced Texture Mapping

> Jürgen P. Schulze, Ph.D. University of California, San Diego Fall Quarter 2020

Announcements

Sunday, November 8th at 11:59pm:

Homework Project 2 due





Aliasing

What could cause this aliasing effect?







Aliasing

Sufficiently sampled, no aliasing

Insufficiently sampled, aliasing



High frequencies in the input data can appear as lower frequencies in the sampled signal



Antialiasing: Intuition

- Pixel may cover large area on triangle in camera space
- Corresponds to many texels in texture space
- Need to compute average



Antialiasing Using Mip-Maps

Averaging over texels is expensive

- Many texels as objects get smaller
- Large memory access and compution cost
- Precompute filtered (averaged) textures
 - Mip-maps
- Practical solution to aliasing problem
 - Fast and simple
 - Available in OpenGL, implemented in GPUs
 - Reasonable quality



MIP stands for multum in parvo = "much in little" (Williams 1983)

Before rendering

- Pre-compute and store down scaled versions of textures
 - Reduce resolution by factors of two successively
 - Use high quality filtering (averaging) scheme
- Increases memory cost by I/3
 - $|/3 = |/4 + |/|6 + |/64 + \dots$
- Width and height of texture should be powers of two (nonpower of two supported since OpenGL 2.0)



Example: resolutions 512x512, 256x256, 128x128, 64x64, 32x32 pixels



 One texel in level 4 is the average of 4⁴=256 texels in level 0





Level 0

Level 1

Level 2





11

Rendering With Mipmaps

- "Mipmapping"
- Interpolate texture coordinates of each pixel as without mipmapping
- Compute approximate size of pixel in texture space
- Look up color in nearest mipmap
 - E.g., if pixel corresponds to 10x10 texels use mipmap level 3
 - Use nearest neighbor or bilinear interpolation as before





Nearest Mipmap, Nearest Neighbor

Visible transition between mipmap levels





Nearest Mipmap, Bilinear

Visible transition between mipmap levels





Trilinear Mipmapping

Use two nearest mipmap levels

E.g., if pixel corresponds to 10x10 texels, use mipmap levels 3 (8x8) and 4 (16x16)

2-Step approach:

- Step I: perform bilinear interpolation in both mip-maps
- Step 2: linearly interpolate between the results
- Requires access to 8 texels for each pixel
- Supported by hardware without performance penalty



Anisotropic Filtering

- Method of enhancing the image quality of textures on surfaces that are at oblique viewing angles
- Different degrees or ratios of anisotropic filtering can be applied
- The degree refers to the maximum ratio of anisotropy supported by the filtering process. For example, 4:1 anisotropic filtering supports presampled textures up to four times wider than tall





More Info

Mipmapping tutorial w/source code:

http://www.videotutorialsrock.com/opengl_tutorial/mipmapping/text.php



Environment Mapping

More Realistic Illumination

In the real world:

At each point in scene light arrives from all directions

- Not just from a few point light sources
- \rightarrow Global Illumination is a solution, but computationally expensive

Environment Maps

- Store "omni-directional" illumination as images
- Each pixel corresponds to light from a certain direction
- Sky boxes make for great environment maps





Capturing Environment Maps

- Environment map = surround panoramic image
- Creating 360 degrees panoramic images:
 - > 360 degree camera
 - "light probe" image: take picture of mirror ball (e.g., silver Christmas ornament)











Light Probes by Paul Debevec http://www.debevec.org/Probes/



Environment Maps as Light Sources

Simplifying Assumption

- Assume light captured by environment map is emitted from infinitely far away
- Environment map consists of directional light sources
 - Value of environment map is defined for each direction, independent of position in scene
- Approach uses same environment map at each point in scene
 - \rightarrow Approximation!



Applications for Environment Maps

Use environment map as "light source"



Global illumination with pre-computed radiance transfer [Sloan et al. 2002]



Reflection mapping [Georg-Simon Ohm University of Applied Sciences]



Cubic Environment Maps

 Store incident light on six faces of a cube instead of on sphere





Cubic vs. Spherical Maps

Advantages of cube maps:

- More even texel sample density causes less distortion, allowing for lower resolution maps
- Easier to dynamically generate cube maps for real-time simulated reflections





Bubble Demo



http://download.nvidia.com/downloads/nZone/demos/nvidia/Bubble.zip



Cubic Environment Maps

Cube map look-up

- ▶ Given: light direction (*x*,*y*,*z*)
- Largest coordinate component determines cube map face
- Dividing by magnitude of largest component yields coordinates within face
- In GLSL:
 - ▶ Use (*x*,*y*,*z*) direction as texture coordinates to samplerCube



Reflection Mapping

- Simulates mirror reflection
- Computes reflection vector at each pixel
- Use reflection vector to look up cube map
- Rendering cube map itself is optional (application dependent)



Reflection mapping



Reflection Mapping in GLSL

Application Setup

Load and bind a cube environment map

glBindTexture(GL_TEXTURE_CUBE_MAP, ...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X,...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_X,...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Y,...);

glEnable(GL_TEXTURE_CUBE_MAP);



Environment Mapping: Concept



Source: http://antongerdelan.net/opengl/cubemaps.html



Environment Mapping: Vertex Shader

```
#version 400
```

```
in vec3 vp; // positions from mesh
in vec3 vn; // normals from mesh
uniform mat4 P, V, M; // proj, view, model matrices
out vec3 pos_eye;
out vec3 n_eye;
void main()
{
    pos_eye = vec3(V * M * vec4(vp, 1.0));
    n_eye = vec3(V * M * vec4(vn, 0.0));
    gl_Position = P * V * M * vec4(vp, 1.0);
}
```



Environment Mapping: Fragment Shader

```
#version 400
```

```
in vec3 pos_eye;
in vec3 n_eye;
uniform samplerCube cube_texture;
uniform mat4 V; // view matrix
out vec4 frag colour;
void main()
  // reflect ray around normal from eye to surface
  vec3 incident_eye = normalize(pos_eye);
  vec3 normal = normalize(n_eye);
  vec3 reflected = reflect(incident_eye, normal);
  // convert from eye to world space
  reflected = vec3(inverse(V) * vec4(reflected, 0.0));
```

```
frag_colour = texture(cube_texture, reflected);
```



Environment Maps as Light Sources

Covered so far: shading of a specular surface

 \rightarrow How do you compute shading of a diffuse surface?



Diffuse Irradiance Environment Map

- Given a scene with k directional lights, light directions $d_1..d_k$ and intensities $i_1..i_k$, illuminating a diffuse surface with normal n and color c
- Pixel intensity B is computed as: $B = c \sum_{j=1..k} \max(0, d_j \cdot n) i_j$
- Cost of computing B proportional to number of texels in environment map!
- \rightarrow Precomputation of diffuse reflection
- Observations:
 - All surfaces with normal direction *n* will return the same value for the sum
 - The sum is dependent on just the lights in the scene and the surface normal
- Precompute sum for any normal n and store result in a second environment map, indexed by surface normal
- Second environment map is called diffuse irradiance environment map
- Allows to illuminate objects with arbitrarily complex lighting environments with single texture lookup



Diffuse Irradiance Environment Map

- Two cubic environment maps:
 - Reflection map
 - Diffuse map



Diffuse shading vs. shading w/diffuse map



Image source: http://http.developer.nvidia.com/GPUGems2/gpugems2_chapter10.html



