

CSE 167:
Introduction to Computer Graphics
Lecture #10: Culling

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Lecture Overview

- ▶ Culling

Culling

- ▶ Goal:

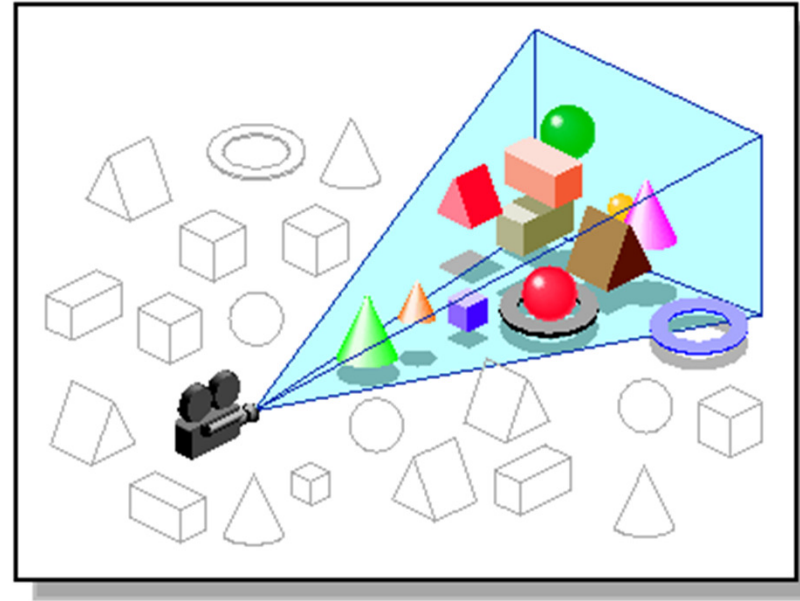
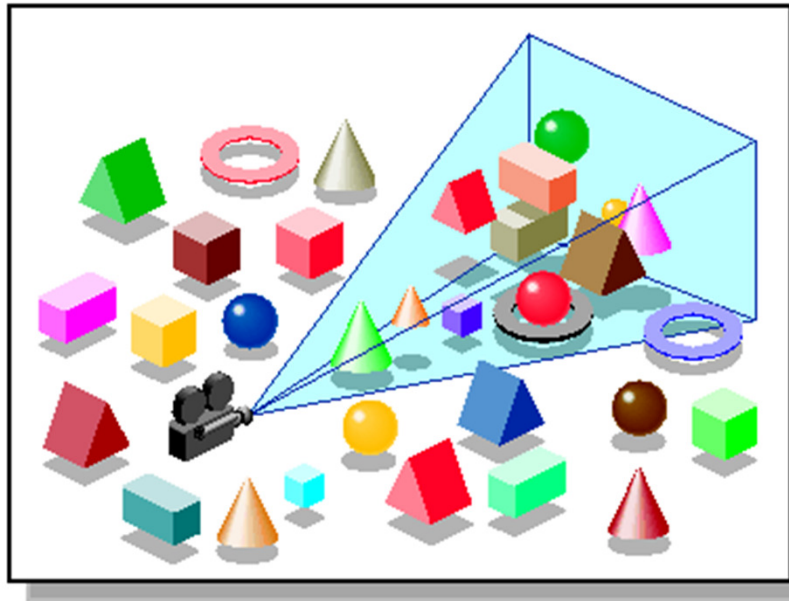
Discard geometry that does not need to be drawn to speed up rendering

- ▶ Types of culling:

- ▶ View frustum culling
- ▶ Occlusion culling
- ▶ Small object culling
- ▶ Backface culling
- ▶ Degenerate culling

View Frustum Culling

- ▶ Triangles outside of view frustum are off-screen
 - ▶ Done on canonical view volume



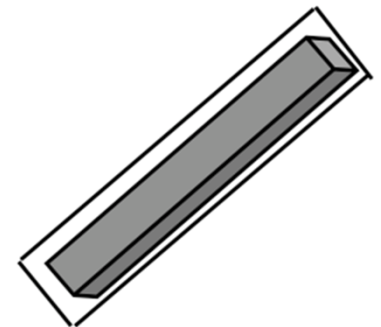
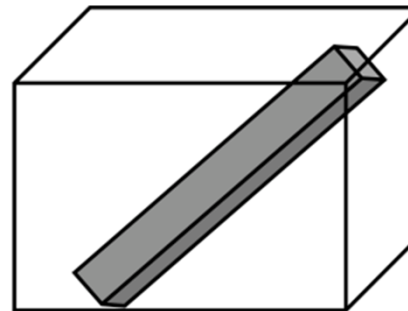
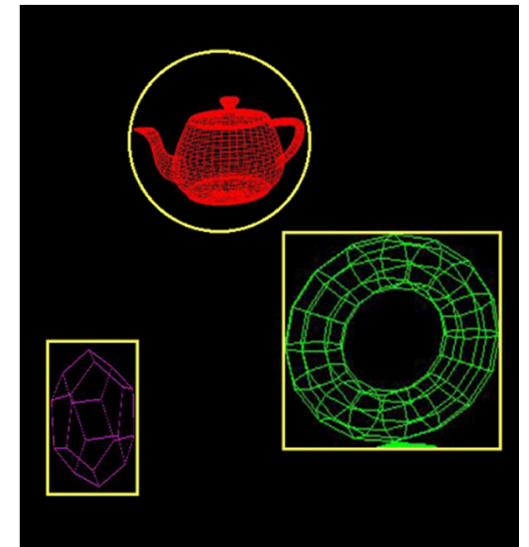
Images: SGI OpenGL Optimizer Programmer's Guide

Videos

- ▶ Rendering Optimizations - Frustum Culling
 - ▶ <http://www.youtube.com/watch?v=kvVHp9wMAO8>
- ▶ View Frustum Culling Demo
 - ▶ <http://www.youtube.com/watch?v=bJrYTBGpwic>

Bounding Volumes

- ▶ Simple shape that completely encloses an object
- ▶ Generally a box or sphere
- ▶ We use spheres
 - ▶ Easiest to work with
 - ▶ But hard to calculate tight fits
- ▶ Intersect bounding volume with view frustum instead of each primitive



Bounding Box

- ▶ How to cull objects consisting of many polygons?
- ▶ Cull bounding box
 - ▶ Rectangular box, parallel to object space coordinate planes
 - ▶ Box is smallest box containing the entire object

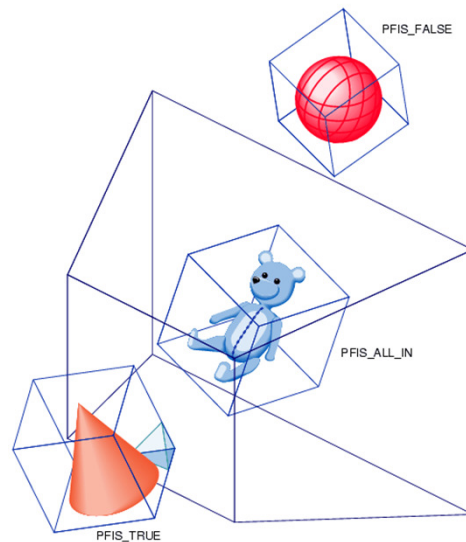
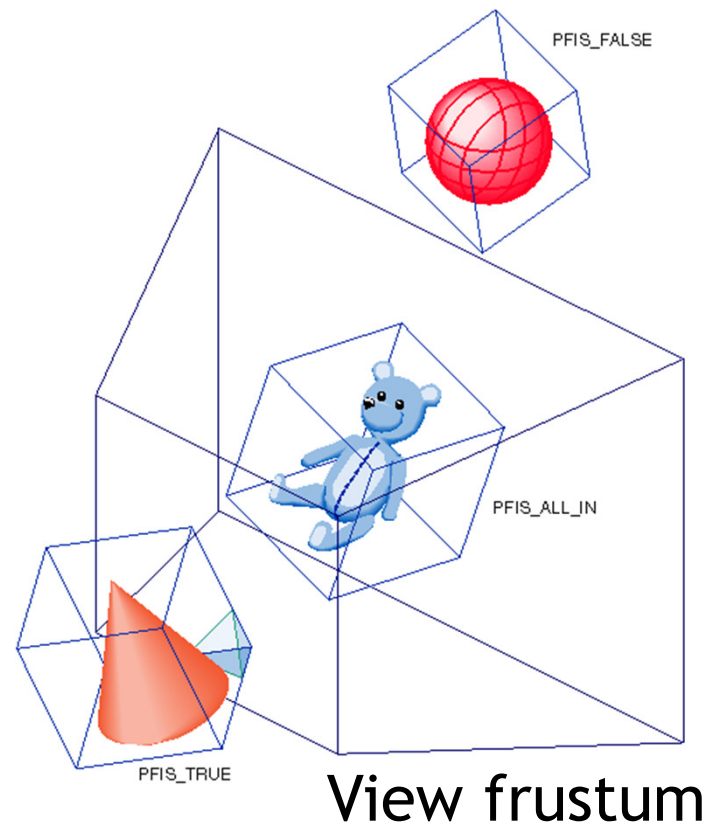


Image: SGI OpenGL Optimizer Programmer's Guide

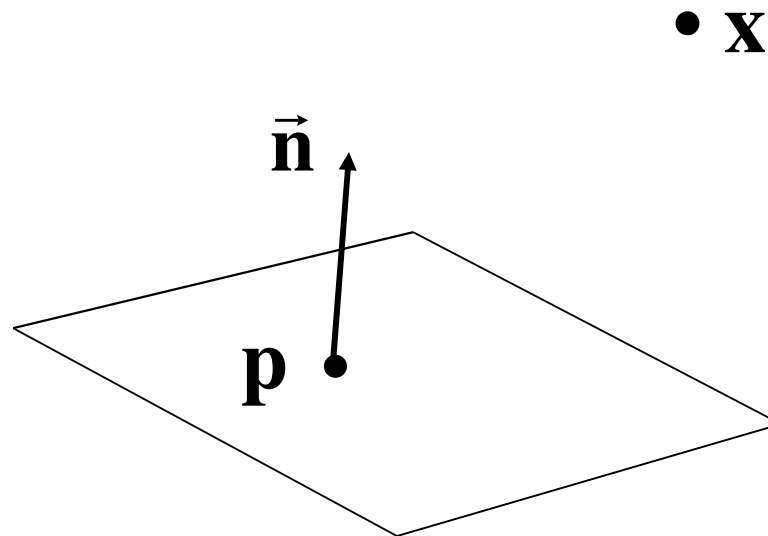
View Frustum Culling

- ▶ Frustum defined by 6 planes
- ▶ Each plane divides space into “outside”, “inside”
- ▶ Check each object against each plane
 - ▶ Outside, inside, intersecting
- ▶ If “outside” all planes
 - ▶ Outside the frustum
- ▶ If “inside” all planes
 - ▶ Inside the frustum
- ▶ Else partly inside and partly out
- ▶ Efficiency



Distance to Plane

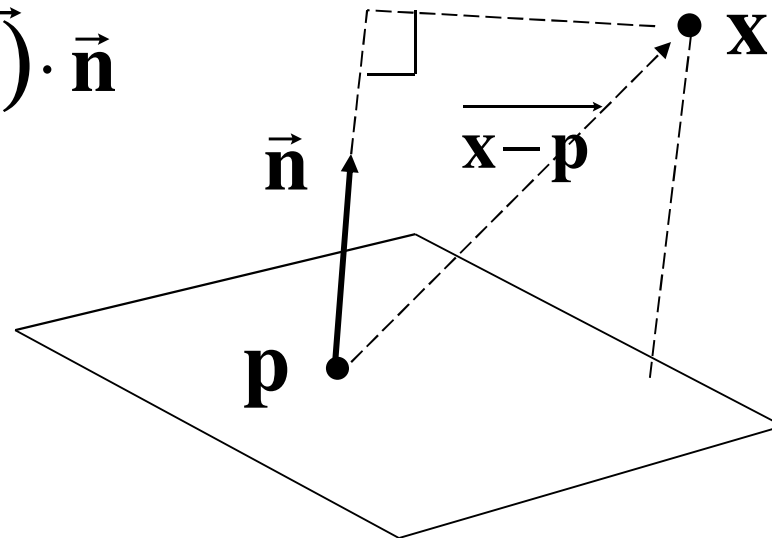
- ▶ A plane is described by a point \mathbf{p} on the plane and a unit normal \mathbf{n}
- ▶ Find the (perpendicular) distance from point \mathbf{x} to the plane



Distance to Plane

- ▶ The distance is the length of the projection of $\mathbf{x} - \mathbf{p}$ onto \mathbf{n}

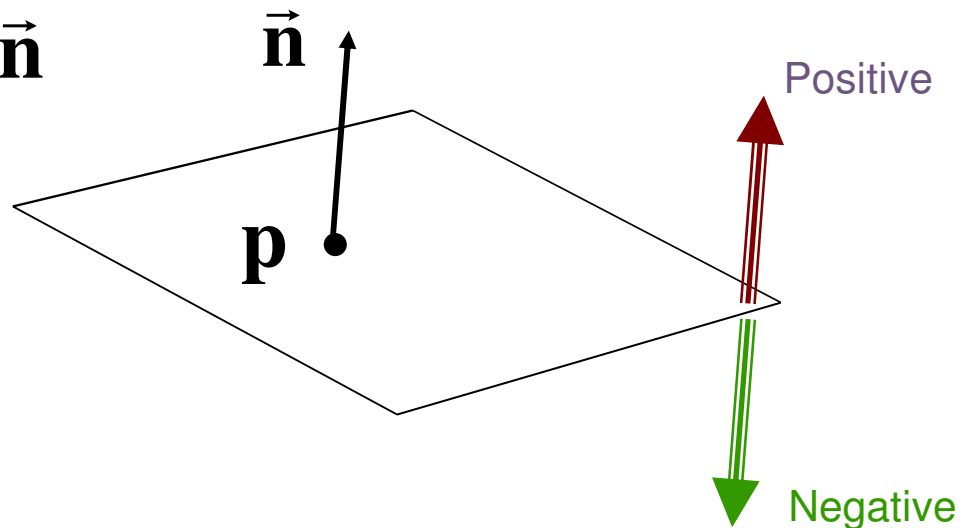
$$dist = (\mathbf{x} - \mathbf{p}) \cdot \vec{\mathbf{n}}$$



Distance to Plane

- ▶ The distance has a sign
 - ▶ positive on the side of the plane the normal points to
 - ▶ negative on the opposite side
 - ▶ zero exactly on the plane
- ▶ Divides 3D space into two infinite half-spaces

$$dist(\mathbf{x}) = \overrightarrow{(\mathbf{x} - \mathbf{p})} \cdot \vec{\mathbf{n}}$$



Distance to Plane

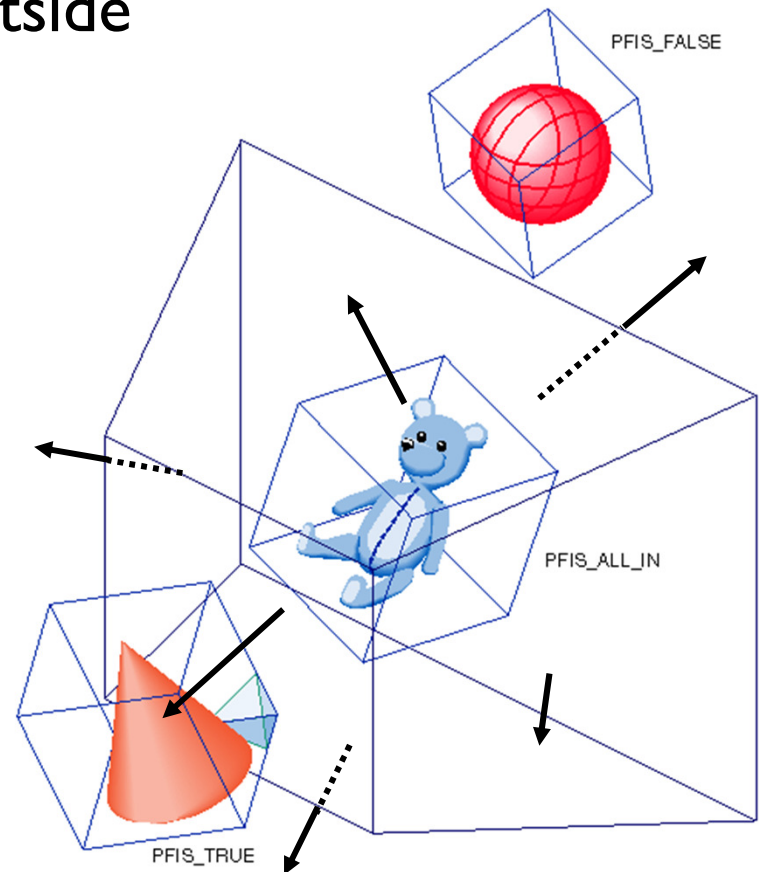
- ▶ Simplification

$$\begin{aligned}dist(\mathbf{x}) &= (\mathbf{x} - \mathbf{p}) \cdot \mathbf{n} \\&= \mathbf{x} \cdot \mathbf{n} - \mathbf{p} \cdot \mathbf{n} \\dist(\mathbf{x}) &= \mathbf{x} \cdot \mathbf{n} - d, \quad d = \mathbf{p} \cdot \mathbf{n}\end{aligned}$$

- ▶ d is independent of \mathbf{x}
- ▶ d is distance from the origin to the plane
- ▶ We can represent a plane with just d and \mathbf{n}

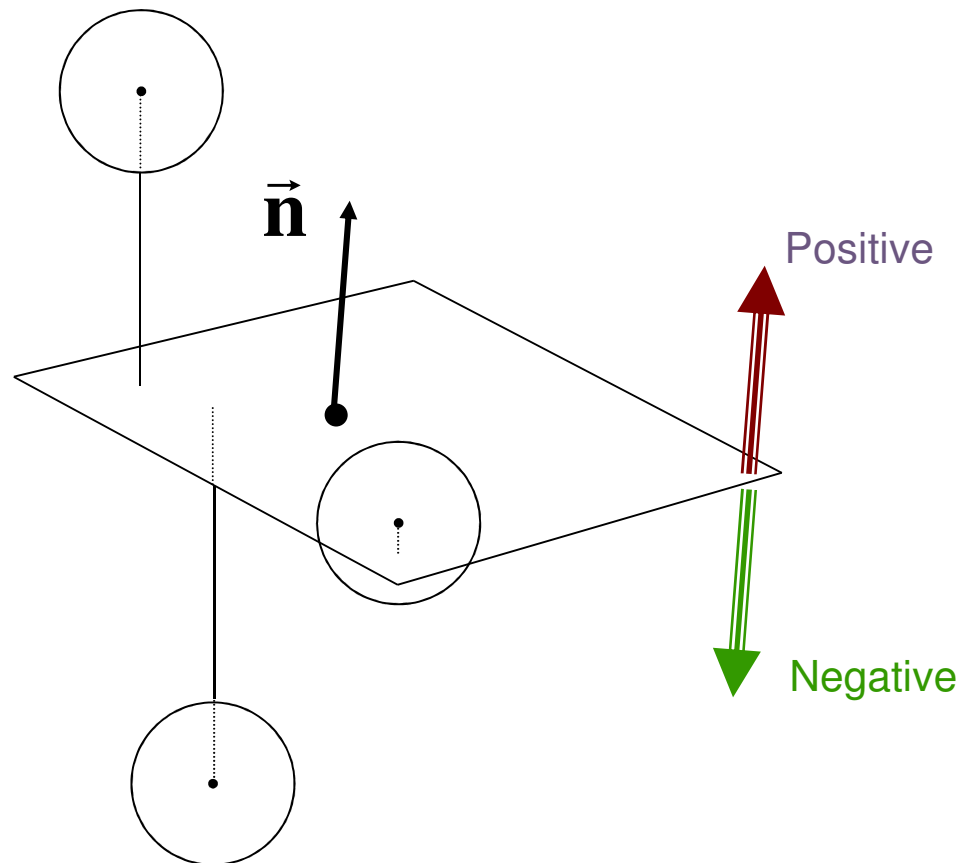
Frustum With Signed Planes

- ▶ Normal of each plane points outside
 - ▶ “outside” means positive distance
 - ▶ “inside” means negative distance



Test Sphere and Plane

- ▶ For sphere with radius r and origin \mathbf{x} , test the distance to the origin, and see if it is beyond the radius
- ▶ Three cases:
 - ▶ $\text{dist}(\mathbf{x}) > r$
 - ▶ completely above
 - ▶ $\text{dist}(\mathbf{x}) < -r$
 - ▶ completely below
 - ▶ $-r < \text{dist}(\mathbf{x}) < r$
 - ▶ intersects

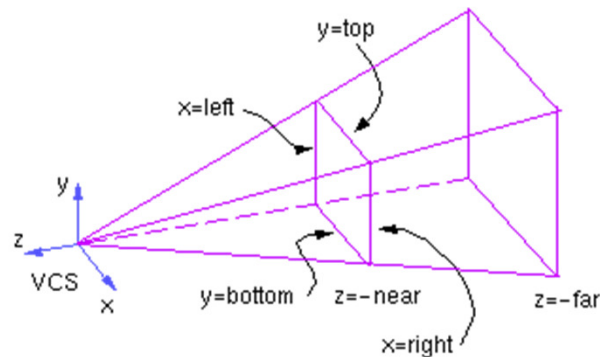


Culling Summary

- ▶ Pre-compute the normal \mathbf{n} and value d for each of the six planes.
- ▶ Given a sphere with center \mathbf{x} and radius r
- ▶ For each plane:
 - ▶ if $dist(\mathbf{x}) > r$: sphere is outside! (no need to continue loop)
 - ▶ add 1 to count if $dist(\mathbf{x}) < -r$
- ▶ If we made it through the loop, check the count:
 - ▶ if the count is 6, the sphere is completely inside
 - ▶ otherwise the sphere intersects the frustum
 - ▶ (*can use a flag instead of a count*)

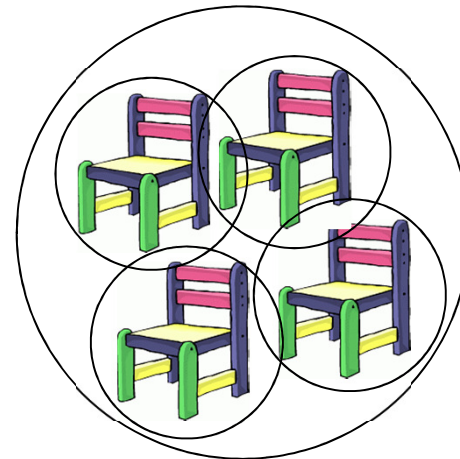
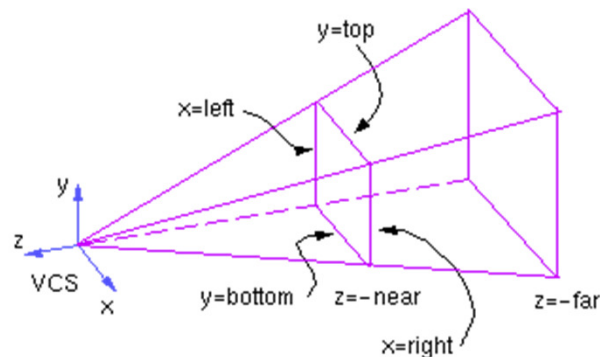
Culling Groups of Objects

- ▶ Want to be able to cull the whole group quickly
- ▶ But if the group is partly in and partly out, want to be able to cull individual objects



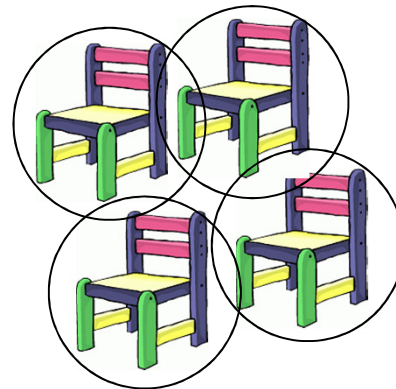
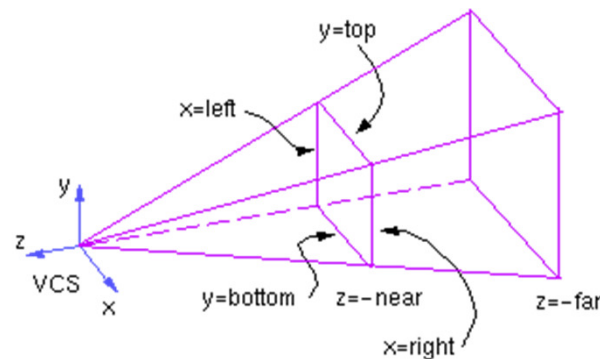
Hierarchical Bounding Volumes

- ▶ Given hierarchy of objects
- ▶ Bounding volume of each node encloses the bounding volumes of all its children
- ▶ Start by testing the outermost bounding volume
 - ▶ If it is entirely outside, don't draw the group at all
 - ▶ If it is entirely inside, draw the whole group



Hierarchical Culling

- ▶ If the bounding volume is partly inside and partly outside
 - ▶ Test each child's bounding volume individually
 - ▶ If the child is in, draw it; if it's out cull it; if it's partly in and partly out, recurse.
 - ▶ If recursion reaches a leaf node, draw it normally



Video

- ▶ Math for Game Developers - Frustum Culling
 - ▶ http://www.youtube.com/watch?v=4p-E_3IXOPM

