CSE 167: Introduction to Computer Graphics Lecture #14: Surface Patches

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Announcements

This Thursday: midterm exam

- In-class
- Closed book
- This Friday: late grading for project 6
- Sunday: first blog for final project due



Final Project

http://ivl.calit2.net/wiki/index.php/Project7SP15



Overview

- Bi-linear patch
- Bi-cubic Bézier patch
- Advanced parametric surfaces



Curved Surfaces

Curves

- Described by a ID series of control points
- A function $\mathbf{x}(t)$
- Segments joined together to form a longer curve

Surfaces

- Described by a 2D mesh of control points
- Parameters have two dimensions (two dimensional parameter domain)
- A function $\mathbf{x}(u, v)$
- Patches joined together to form a bigger surface



Parametric Surface Patch

• $\mathbf{x}(u,v)$ describes a point in space for any given (u,v) pair

▶ *u*,*v* each range from 0 to 1





Parametric Surface Patch

x(u,v) describes a point in space for any given (u,v) pair
u,v each range from 0 to 1



Parametric curves

2D parameter domain

- For fixed u_0 , have a v curve $\mathbf{x}(u_0, v)$
- For fixed v_0 , have a u curve $\mathbf{x}(u, v_0)$
- For any point on the surface, there are a pair of parametric curves through that point



Tangents

- The tangent to a parametric curve is also tangent to the surface
- For any point on the surface, there are a pair of (parametric) tangent vectors
- Note: these vectors are not necessarily perpendicular to each other





Tangents

• Notation:

• The tangent along a *u* curve, AKA the tangent in the *u* direction, is written as:

$$\frac{\partial \mathbf{x}}{\partial u}(u,v)$$
 or $\frac{\partial}{\partial u}\mathbf{x}(u,v)$ or $\mathbf{x}_u(u,v)$

• The tangent along a v curve, AKA the tangent in the v direction, is written as:

$$\frac{\partial \mathbf{x}}{\partial v}(u,v)$$
 or $\frac{\partial}{\partial v}\mathbf{x}(u,v)$ or $\mathbf{x}_{v}(u,v)$

- Note that each of these is a vector-valued function:
 - At each point $\mathbf{x}(u,v)$ on the surface, we have tangent vectors $\frac{\partial}{\partial u}\mathbf{x}(u,v)$ and $\frac{\partial}{\partial v}\mathbf{x}(u,v)$



Surface Normal

- Normal is cross product of the two tangent vectors
- Order matters!



$$\vec{\mathbf{n}}(u,v) = \frac{\partial \mathbf{x}}{\partial u}(u,v) \times \frac{\partial \mathbf{x}}{\partial v}(u,v)$$

Typically we are interested in the unit normal, so we need to normalize

$$\vec{\mathbf{n}}^{*}(u,v) = \frac{\partial \mathbf{x}}{\partial u}(u,v) \times \frac{\partial \mathbf{x}}{\partial v}(u,v)$$
$$\vec{\mathbf{n}}(u,v) = \frac{\vec{\mathbf{n}}^{*}(u,v)}{\left|\vec{\mathbf{n}}^{*}(u,v)\right|}$$

- Control mesh with four points $\mathbf{p}_0, \mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3$
- Compute $\mathbf{x}(u,v)$ using a two-step construction scheme





Bilinear Patch (Step 1)

- For a given value of u, evaluate the linear curves on the two udirection edges
- Use the same value *u* for both:



Bilinear Patch (Step 2)

- Consider that q_0, q_1 define a line segment
- Evaluate it using v to get x

 $\mathbf{x} = Lerp(v, \mathbf{q}_0, \mathbf{q}_1)$





Combining the steps, we get the full formula

 $\mathbf{x}(u,v) = Lerp(v, Lerp(u, \mathbf{p}_0, \mathbf{p}_1), Lerp(u, \mathbf{p}_2, \mathbf{p}_3))$





- Try the other order
- Evaluate first in the v direction

$$\mathbf{r}_0 = Lerp(v, \mathbf{p}_0, \mathbf{p}_2)$$
 $\mathbf{r}_1 = Lerp(v, \mathbf{p}_1, \mathbf{p}_3)$





• Consider that \mathbf{r}_0 , \mathbf{r}_1 define a line segment

• Evaluate it using u to get \mathbf{x}

$$\mathbf{x} = Lerp(u, \mathbf{r}_0, \mathbf{r}_1)$$





• The full formula for the *v* direction first:

 $\mathbf{x}(u,v) = Lerp(u, Lerp(v, \mathbf{p}_0, \mathbf{p}_2), Lerp(v, \mathbf{p}_1, \mathbf{p}_3))$





Patch geometry is independent of the order of u and v

$$\mathbf{x}(u,v) = Lerp(v, Lerp(u, \mathbf{p}_0, \mathbf{p}_1), Lerp(u, \mathbf{p}_2, \mathbf{p}_3))$$
$$\mathbf{x}(u,v) = Lerp(u, Lerp(v, \mathbf{p}_0, \mathbf{p}_2), Lerp(v, \mathbf{p}_1, \mathbf{p}_3))$$





Visualization





- Weighted sum of control points $\mathbf{x}(u,v) = (1-u)(1-v)\mathbf{p}_0 + u(1-v)\mathbf{p}_1 + (1-u)v\mathbf{p}_2 + uv\mathbf{p}_3$
- Bilinear polynomial

 $\mathbf{x}(u,v) = (\mathbf{p}_0 - \mathbf{p}_1 - \mathbf{p}_2 + \mathbf{p}_3)uv + (\mathbf{p}_1 - \mathbf{p}_0)u + (\mathbf{p}_2 - \mathbf{p}_0)v + \mathbf{p}_0$

Matrix form

$$x(u,v) = \begin{bmatrix} 1-u & u \end{bmatrix} \begin{bmatrix} p_0 & p_2 \\ p_1 & p_3 \end{bmatrix} \begin{bmatrix} 1-v \\ v \end{bmatrix}$$



Properties

- Interpolates the control points
- The boundaries are straight line segments
- If all 4 points of the control mesh are co-planar, the patch is flat
- If the points are not co-planar, we get a curved surface
 - saddle shape (hyperbolic paraboloid)
- The parametric curves are all straight line segments!
 - a (doubly) ruled surface: has (two) straight lines through every point



Not terribly useful as a modeling primitive



Overview

- Bi-linear patch
- Bi-cubic Bézier patch
- Advanced parametric surfaces



Bicubic Bézier patch

- Grid of 4x4 control points, \mathbf{p}_0 through \mathbf{p}_{15}
- Four rows of control points define Bézier curves along u p₀,p₁,p₂,p₃; p₄,p₅,p₆,p₇; p₈,p₉,p₁₀,p₁₁; p₁₂,p₁₃,p₁₄,p₁₅
- Four columns define Bézier curves along v p₀,p₄,p₈,p₁₂; p₁,p₆,p₉,p₁₃; p₂,p₆,p₁₀,p₁₄; p₃,p₇,p₁₁,p₁₅





Bézier Patch (Step 1)

- Evaluate four *u*-direction Bézier curves at scalar value *u* [0..1]
- Get points $\mathbf{q}_0 \dots \mathbf{q}_3$ $\mathbf{q}_0 = Bez(u, \mathbf{p}_0, \mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3)$ $\mathbf{q}_1 = Bez(u, \mathbf{p}_4, \mathbf{p}_5, \mathbf{p}_6, \mathbf{p}_7)$ $\mathbf{q}_2 = Bez(u, \mathbf{p}_8, \mathbf{p}_9, \mathbf{p}_{10}, \mathbf{p}_{11})$ $\mathbf{q}_3 = Bez(u, \mathbf{p}_{12}, \mathbf{p}_{13}, \mathbf{p}_{14}, \mathbf{p}_{15})$





Bézier Patch (Step 2)

> Points $\mathbf{q}_{0 \dots} \mathbf{q}_{3}$ define a Bézier curve

• Evaluate it at v [0..1] $\mathbf{x}(u,v) = Bez(v,\mathbf{q}_0,\mathbf{q}_1,\mathbf{q}_2,\mathbf{q}_3)$





Bézier Patch

Same result in either order (evaluate *u* before *v* or vice versa)





Bézier Patch: Matrix Form

$$\mathbf{U} = \begin{bmatrix} u^{3} \\ u^{2} \\ u \\ 1 \end{bmatrix} \quad \mathbf{V} = \begin{bmatrix} v^{3} \\ v^{2} \\ v \\ 1 \end{bmatrix} \quad \mathbf{B}_{Bez} = \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \mathbf{B}_{Bez}^{T}$$
$$\mathbf{C}_{x} = \mathbf{B}_{Bez}^{T} \mathbf{G}_{x} \mathbf{B}_{Bez} \quad \mathbf{G}_{x} = \begin{bmatrix} p_{0x} & p_{1x} & p_{2x} & p_{3x} \\ p_{4x} & p_{5x} & p_{6x} & p_{7x} \\ p_{8x} & p_{9x} & p_{10x} & p_{11x} \\ p_{12x} & p_{13x} & p_{14x} & p_{15x} \end{bmatrix}, \quad \mathbf{G}_{y} = \cdots, \quad \mathbf{G}_{z} = \cdots$$

$$\mathbf{x}(u,v) = \begin{bmatrix} \mathbf{V}^T \mathbf{C}_x \mathbf{U} \\ \mathbf{V}^T \mathbf{C}_y \mathbf{U} \\ \mathbf{V}^T \mathbf{C}_z \mathbf{U} \end{bmatrix}$$

Bézier Patch: Matrix Form

- C_x stores the coefficients of the bicubic equation for x
- \mathbf{C}_{y} stores the coefficients of the bicubic equation for y
- \mathbf{C}_{z} stores the coefficients of the bicubic equation for z
- $\mathbf{G}_{\mathbf{x}}$ stores the geometry (x components of the control points)
- \mathbf{G}_{y} stores the geometry (y components of the control points)
- \mathbf{G}_{z} stores the geometry (z components of the control points)
- **B**_{Bez} is the basis matrix (Bézier basis)
- **U** and **V** are the vectors formed from the powers of u and v
- Compact notation
- Leads to efficient method of computation
- Can take advantage of hardware support for 4x4 matrix arithmetic



Properties

- Convex hull: any point on the surface will fall within the convex hull of the control points
- Interpolates 4 corner points
- Approximates other 12 points, which act as "handles"
- The boundaries of the patch are the Bézier curves defined by the points on the mesh edges
- The parametric curves are all Bézier curves









Tangents of a Bézier patch

- Remember parametric curves x(u,v₀), x(u₀,v) where v₀, u₀ is fixed
- Tangents to surface = tangents to parametric curves
- Tangents are partial derivatives of $\mathbf{x}(u, v)$
- Normal is cross product of the tangents



Tangents of a Bézier patch





Tessellating a Bézier patch

Uniform tessellation is most straightforward

- Evaluate points on a grid of *u*, *v* coordinates
- Compute tangents at each point, take cross product to get per-vertex normal
- Draw triangle strips with glBegin(GL_TRIANGLE_STRIP)



- Adaptive tessellation/recursive subdivision
 - Potential for "cracks" if patches on opposite sides of an edge divide differently
 - Tricky to get right, but can be done



Piecewise Bézier Surface

- Lay out grid of adjacent meshes of control points
- For C^0 continuity, must share points on the edge
 - Each edge of a Bézier patch is a Bézier curve based only on the edge mesh points
 - So if adjacent meshes share edge points, the patches will line up exactly
- But we have a crease...







C¹ Continuity

- We want the parametric curves that cross each edge to have C¹ continuity
 - > So the handles must be equal-and-opposite across the edge:





http://www.spiritone.com/~english/cyclopedia/patches.html



Modeling With Bézier Patches

- Original Utah teapot, from Martin Newell's PhD thesis, consisted of 28 Bézier patches.
- The original had no rim for the lid and no bottom
- Later, four more patches were added to create a bottom, bringing the total to 32
- The data set was used by a number of people, including graphics guru Jim Blinn. In a demonstration of a system of his he scaled the teapot by .75, creating a stubbier teapot. He found it more pleasing to the eye, and it was this scaled version that became the highly popular dataset used today.

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Source: http://www.holmes3d.net/graphics/teapot/



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Problems with Bezier and NURBS Patches

NURBS surfaces are versatile

- Conic sections
- Can blend, merge, trim...

But:

 Any surface will be made of quadrilateral patches (quadrilateral topology)

This makes it hard to

- Join or abut curved pieces
- Build surfaces with complex topology or structure





