# CSE 167: <br> Introduction to Computer Graphics Lecture \#14: Surface Patches 

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## Announcements

- This Thursday: midterm exam
- In-class
- Closed book
- This Friday: late grading for project 6
- Sunday: first blog for final project due


## Final Project

- http://ivl.calit2.net/wiki/index.php/Project7SPI5


## Overview

- Bi-linear patch
- Bi-cubic Bézier patch
- Advanced parametric surfaces


## Curved Surfaces

## Curves

- Described by a ID series of control points
- A function $\mathbf{x}(t)$
- Segments joined together to form a longer curve


## Surfaces

- Described by a 2D mesh of control points
- Parameters have two dimensions (two dimensional parameter domain)
- A function $\mathbf{x}(u, v)$
- Patches joined together to form a bigger surface


## Parametric Surface Patch

- $\mathbf{x}(u, v)$ describes a point in space for any given ( $u, v$ ) pair
- $u, v$ each range from 0 to I


2D parameter domain

## Parametric Surface Patch

- $\mathbf{x}(u, v)$ describes a point in space for any given $(u, v)$ pair

। $u, v$ each range from 0 to I


- Parametric curves

2D parameter domain

- For fixed $u_{0}$, have a $v$ curve $\mathbf{x}\left(u_{0}, v\right)$
- For fixed $v_{0}$, have a $u$ curve $\mathbf{x}\left(u, v_{0}\right)$
- For any point on the surface, there are a pair of parametric curves through that point


## Tangents

- The tangent to a parametric curve is also tangent to the surface
- For any point on the surface, there are a pair of (parametric) tangent vectors
- Note: these vectors are not necessarily perpendicular to each other



## Tangents

- Notation:
- The tangent along a $u$ curve, AKA the tangent in the $u$ direction, is written as:

$$
\frac{\partial \mathbf{x}}{\partial u}(u, v) \text { or } \frac{\partial}{\partial u} \mathbf{x}(u, v) \text { or } \mathbf{x}_{u}(u, v)
$$

- The tangent along a $v$ curve, AKA the tangent in the $v$ direction, is written as:

$$
\frac{\partial \mathbf{x}}{\partial v}(u, v) \text { or } \frac{\partial}{\partial v} \mathbf{x}(u, v) \text { or } \mathbf{x}_{v}(u, v)
$$

- Note that each of these is a vector-valued function:
- At each point $\mathbf{x}(u, v)$ on the surface, we have tangent vectors $\frac{\partial}{\partial u} \mathbf{x}(u, v)$ and $\frac{\partial}{\partial v} \mathbf{x}(u, v)$


## Surface Normal

- Normal is cross product of the two tangent vectors
, Order matters!


$$
\overrightarrow{\mathbf{n}}(u, v)=\frac{\partial \mathbf{x}}{\partial u}(u, v) \times \frac{\partial \mathbf{x}}{\partial v}(u, v)
$$

Typically we are interested in the unit normal, so we need to normalize

$$
\begin{aligned}
& \overrightarrow{\mathbf{n}}^{*}(u, v)=\frac{\partial \mathbf{x}}{\partial u}(u, v) \times \frac{\partial \mathbf{x}}{\partial v}(u, v) \\
& \overrightarrow{\mathbf{n}}(u, v)=\frac{\overrightarrow{\mathbf{n}}^{*}(u, v)}{\left|\overrightarrow{\mathbf{n}}^{*}(u, v)\right|}
\end{aligned}
$$

## Bilinear Patch

- Control mesh with four points $\mathbf{p}_{0}, \mathbf{p}_{1}, \mathbf{p}_{2}, \mathbf{p}_{3}$
- Compute $\mathbf{x}(u, v)$ using a two-step construction scheme



## Bilinear Patch (Step 1)

- For a given value of $u$, evaluate the linear curves on the two $u$ direction edges
- Use the same value $u$ for both:



## Bilinear Patch (Step 2)

- Consider that $\mathbf{q}_{0}, \mathbf{q}_{1}$ define a line segment
- Evaluate it using $v$ to get $\mathbf{x}$

$$
\mathbf{x}=\operatorname{Lerp}\left(v, \mathbf{q}_{0}, \mathbf{q}_{1}\right)
$$



## Bilinear Patch

- Combining the steps, we get the full formula

$$
\mathbf{x}(u, v)=\operatorname{Lerp}\left(v, \operatorname{Lerp}\left(u, \mathbf{p}_{0}, \mathbf{p}_{1}\right), \operatorname{Lerp}\left(u, \mathbf{p}_{2}, \mathbf{p}_{3}\right)\right)
$$



## Bilinear Patch

- Try the other order
- Evaluate first in the $v$ direction

$$
\mathbf{r}_{0}=\operatorname{Lerp}\left(v, \mathbf{p}_{0}, \mathbf{p}_{2}\right) \quad \mathbf{r}_{1}=\operatorname{Lerp}\left(v, \mathbf{p}_{1}, \mathbf{p}_{3}\right)
$$



## Bilinear Patch

- Consider that $\mathbf{r}_{0}, \mathbf{r}_{1}$ define a line segment
- Evaluate it using $u$ to get $\mathbf{x}$

$$
\mathbf{x}=\operatorname{Lerp}\left(u, \mathbf{r}_{0}, \mathbf{r}_{1}\right)
$$



## Bilinear Patch

- The full formula for the $v$ direction first:

$$
\mathbf{x}(u, v)=\operatorname{Lerp}\left(u, \operatorname{Lerp}\left(v, \mathbf{p}_{0}, \mathbf{p}_{2}\right), \operatorname{Lerp}\left(v, \mathbf{p}_{1}, \mathbf{p}_{3}\right)\right)
$$



## Bilinear Patch

- Patch geometry is independent of the order of $u$ and $v$

$$
\begin{aligned}
& \mathbf{x}(u, v)=\operatorname{Lerp}\left(v, \operatorname{Lerp}\left(u, \mathbf{p}_{0}, \mathbf{p}_{1}\right), \operatorname{Lerp}\left(u, \mathbf{p}_{2}, \mathbf{p}_{3}\right)\right) \\
& \mathbf{x}(u, v)=\operatorname{Lerp}\left(u, \operatorname{Lerp}\left(v, \mathbf{p}_{0}, \mathbf{p}_{2}\right), \operatorname{Lerp}\left(v, \mathbf{p}_{1}, \mathbf{p}_{3}\right)\right)
\end{aligned}
$$



## Bilinear Patch

- Visualization



## Bilinear Patches

- Weighted sum of control points

$$
\mathbf{x}(u, v)=(1-u)(1-v) \mathbf{p}_{0}+u(1-v) \mathbf{p}_{1}+(1-u) v \mathbf{p}_{2}+u v \mathbf{p}_{3}
$$

- Bilinear polynomial

$$
\mathbf{x}(u, v)=\left(\mathbf{p}_{0}-\mathbf{p}_{1}-\mathbf{p}_{2}+\mathbf{p}_{3}\right) u v+\left(\mathbf{p}_{1}-\mathbf{p}_{0}\right) u+\left(\mathbf{p}_{2}-\mathbf{p}_{0}\right) v+\mathbf{p}_{0}
$$

- Matrix form

$$
x(u, v)=\left[\begin{array}{ll}
1-u & u
\end{array}\right]\left[\begin{array}{ll}
p_{0} & p_{2} \\
p_{1} & p_{3}
\end{array}\right]\left[\begin{array}{c}
1-v \\
v
\end{array}\right]
$$

## Properties

- Interpolates the control points
- The boundaries are straight line segments
- If all 4 points of the control mesh are co-planar, the patch is flat
- If the points are not co-planar, we get a curved surface
- saddle shape (hyperbolic paraboloid)
- The parametric curves are all straight line segments!
- a (doubly) ruled surface: has (two) straight lines through every point

- Not terribly useful as a modeling primitive

Overview

- Bi-linear patch
- Bi-cubic Bézier patch
- Advanced parametric surfaces


## Bicubic Bézier patch

- Grid of $4 \times 4$ control points, $\mathbf{p}_{0}$ through $\mathbf{p}_{15}$
- Four rows of control points define Bézier curves along $u$ $\mathbf{p}_{\mathbf{0}}, \mathbf{p}_{\mathbf{1}}, \mathbf{p}_{\mathbf{2}}, \mathbf{p}_{\mathbf{3}} ; \mathbf{p}_{4}, \mathbf{p}_{5}, \mathbf{p}_{6}, \mathbf{p}_{7} ; \mathbf{p}_{\mathbf{8}}, \mathbf{p}_{9}, \mathbf{p}_{\mathbf{1 0}}, \mathbf{p}_{11} ; \mathbf{p}_{12}, \mathbf{p}_{13}, \mathbf{p}_{14}, \mathbf{p}_{15}$
- Four columns define Bézier curves along $v$ $\mathbf{p}_{0}, \mathbf{p}_{4}, \mathbf{p}_{8}, \mathbf{p}_{12} ; \mathbf{p}_{1}, \mathbf{p}_{6}, \mathbf{p}_{9}, \mathbf{p}_{13} ; \mathbf{p}_{2}, \mathbf{p}_{6}, \mathbf{p}_{10}, \mathbf{p}_{14} ; \mathbf{p}_{3}, \mathbf{p}_{7}, \mathbf{p}_{11}, \mathbf{p}_{15}$



## Bézier Patch (Step 1)

- Evaluate four $u$-direction Bézier curves at scalar value $u$ [0..1]
- Get points $\mathbf{q}_{0} \ldots \mathbf{q}_{3} \quad \mathbf{q}_{0}=\operatorname{Bez}\left(u, \mathbf{p}_{0}, \mathbf{p}_{1}, \mathbf{p}_{2}, \mathbf{p}_{3}\right)$

$$
\begin{aligned}
& \mathbf{q}_{1}=\operatorname{Bez}\left(u, \mathbf{p}_{4}, \mathbf{p}_{5}, \mathbf{p}_{6}, \mathbf{p}_{7}\right) \\
& \mathbf{q}_{2}=\operatorname{Bez}\left(u, \mathbf{p}_{8}, \mathbf{p}_{9}, \mathbf{p}_{10}, \mathbf{p}_{11}\right) \\
& \mathbf{q}_{3}=\operatorname{Bez}\left(u, \mathbf{p}_{12}, \mathbf{p}_{13}, \mathbf{p}_{14}, \mathbf{p}_{15}\right)
\end{aligned}
$$



## Bézier Patch (Step 2)

- Points $\mathbf{q}_{0} \ldots \mathbf{q}_{3}$ define a Bézier curve
- Evaluate it at $v[0 . .1]$

$$
\mathbf{x}(u, v)=\operatorname{Bez}\left(v, \mathbf{q}_{0}, \mathbf{q}_{1}, \mathbf{q}_{2}, \mathbf{q}_{3}\right)
$$



## Bézier Patch

- Same result in either order (evaluate $u$ before $v$ or vice versa)


Bézier Patch: Matrix Form

$$
\begin{aligned}
\mathbf{U}=\left[\begin{array}{c}
u^{3} \\
u^{2} \\
u \\
1
\end{array}\right] \quad \mathbf{V}=\left[\begin{array}{c}
v^{3} \\
v^{2} \\
v \\
1
\end{array}\right] \quad \mathbf{B}_{B e z}=\left[\begin{array}{cccc}
-1 & 3 & -3 & 1 \\
3 & -6 & 3 & 0 \\
-3 & 3 & 0 & 0 \\
1 & 0 & 0 & 0
\end{array}\right]=\mathbf{B}_{B e z}^{T} \\
\\
\mathbf{C}_{x}=\mathbf{B}_{B e z}^{T} \mathbf{G}_{x} \mathbf{B}_{B e z} \\
\mathbf{C}_{y}=\mathbf{B}_{B e z}^{T} \mathbf{G}_{y} \mathbf{B}_{B e z} \\
\mathbf{C}_{z}=\mathbf{B}_{B e z}^{T} \mathbf{G}_{z} \mathbf{B}_{B e z}
\end{aligned} \quad \mathbf{G}_{x}=\left[\begin{array}{cccc}
p_{0 x} & p_{1 x} & p_{2 x} & p_{3 x} \\
p_{4 x} & p_{5 x} & p_{6 x} & p_{7 x} \\
p_{8 x} & p_{9 x} & p_{10 x} & p_{11 x} \\
p_{12 x} & p_{13 x} & p_{14 x} & p_{15 x}
\end{array}\right], \mathbf{G}_{y}=\cdots, \mathbf{G}_{z}=\cdots,
$$

$$
\mathbf{x}(u, v)=\left[\begin{array}{c}
\mathbf{V}^{T} \mathbf{C}_{x} \mathbf{U} \\
\mathbf{V}^{T} \mathbf{C}_{y} \mathbf{U} \\
\mathbf{V}^{T} \mathbf{C}_{z} \mathbf{U}
\end{array}\right]
$$

## Bézier Patch: Matrix Form

- $\mathbf{C}_{\mathrm{x}}$ stores the coefficients of the bicubic equation for $x$
- $\mathbf{C}_{y}$ stores the coefficients of the bicubic equation for $y$
- $\mathbf{C}_{\mathbf{z}}$ stores the coefficients of the bicubic equation for $z$
- $\mathbf{G}_{x}$ stores the geometry ( $x$ components of the control points)
- $\mathbf{G}_{y}$ stores the geometry ( $y$ components of the control points)
- $\mathbf{G}_{\mathbf{z}}$ stores the geometry ( $z$ components of the control points)
- $\mathbf{B}_{\mathrm{Bez}}$ is the basis matrix (Bézier basis)
v $\mathbf{U}$ and $\mathbf{V}$ are the vectors formed from the powers of $u$ and $v$
- Compact notation
- Leads to efficient method of computation
- Can take advantage of hardware support for $4 \times 4$ matrix arithmetic


## Properties

- Convex hull: any point on the surface will fall within the convex hull of the control points
- Interpolates 4 corner points
- Approximates other 12 points, which act as "handles"
- The boundaries of the patch are the Bézier curves defined by the points on the mesh edges
- The parametric curves are all Bézier curves



## Tangents of a Bézier patch

- Remember parametric curves $\mathbf{x}\left(u, v_{0}\right), \mathbf{x}\left(u_{0}, v\right)$ where $v_{0,} u_{0}$ is fixed
- Tangents to surface $=$ tangents to parametric curves
- Tangents are partial derivatives of $\mathbf{x}(u, v)$
- Normal is cross product of the tangents



## Tangents of a Bézier patch

$$
\begin{array}{cl}
\mathbf{q}_{\mathbf{0}}=\operatorname{Bez}\left(u, \mathbf{p}_{0}, \mathbf{p}_{1}, \mathbf{p}_{2}, \mathbf{p}_{3}\right) & \begin{array}{l}
\mathbf{r}_{\mathbf{0}}=\operatorname{Bez}\left(v, \mathbf{p}_{0}, \mathbf{p}_{4}, \mathbf{p}_{8}, \mathbf{p}_{12}\right) \\
\mathbf{q}_{1}=\operatorname{Bez}\left(u, \mathbf{p}_{4}, \mathbf{p}_{5}, \mathbf{p}_{6}, \mathbf{p}_{7}\right) \\
\mathbf{q}_{2}=\operatorname{Bez}\left(u, \mathbf{p}_{8}, \mathbf{p}_{9}, \mathbf{p}_{10}, \mathbf{p}_{11}\right) \\
\mathbf{q}_{3}=\operatorname{Bez}\left(u, \mathbf{p}_{12}, \mathbf{p}_{13}, \mathbf{p}_{14}, \mathbf{p}_{15}\right) \\
\frac{\partial \mathbf{x}}{\partial v}(u, v)=\operatorname{Bez}\left(v, \mathbf{p}_{1}, \mathbf{p}_{5}, \mathbf{p}_{9}, \mathbf{p}_{13}\right) \\
\mathbf{r}_{2}=\operatorname{Bez}\left(v, \mathbf{p}_{2}, \mathbf{p}_{6}, \mathbf{p}_{10}, \mathbf{p}_{14}\right) \\
\left.\mathbf{r}_{3}\right)
\end{array} \\
\frac{\partial \mathbf{x}}{\partial u}(u, v)=\operatorname{Bez}\left(v, \mathbf{p}_{3}, \mathbf{p}_{7}, \mathbf{p}_{11}, \mathbf{p}_{15}\right)
\end{array}
$$

## Tessellating a Bézier patch

- Uniform tessellation is most straightforward
- Evaluate points on a grid of $u, v$ coordinates
* Compute tangents at each point, take cross product to get per-vertex normal
- Draw triangle strips with gIBegin(GL_TRIANGLE_STRIP)

- Adaptive tessellation/recursive subdivision
- Potential for "cracks" if patches on opposite sides of an edge divide differently
- Tricky to get right, but can be done


## Piecewise Bézier Surface

- Lay out grid of adjacent meshes of control points
- For $\mathrm{C}^{0}$ continuity, must share points on the edge
- Each edge of a Bézier patch is a Bézier curve based only on the edge mesh points
- So if adjacent meshes share edge points, the patches will line up exactly
- But we have a crease...




## $\mathrm{C}^{1}$ Continuity

- We want the parametric curves that cross each edge to have $\mathrm{C}^{1}$ continuity
- So the handles must be equal-and-opposite across the edge:

http://www.spiritone.com/~english/cyclopedia/patches.html


## Modeling With Bézier Patches

- Original Utah teapot, from Martin Newell's PhD thesis, consisted of 28 Bézier patches.
- The original had no rim for the lid and no bottom
- Later, four more patches were added to
 create a bottom, bringing the total to 32
- The data set was used by a number of people, including graphics guru Jim Blinn. In a demonstration of a system of his he scaled the teapot by .75 , creating
 a stubbier teapot. He found it more pleasing to the eye, and it was this scaled version that became the highly popular dataset used today.

Overview

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- Bi-cubic Bézier patch
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## Problems with Bezier and NURBS Patches

- NURBS surfaces are versatile
- Conic sections
- Can blend, merge, trim...
- But:
- Any surface will be made of quadrilateral patches (quadrilateral topology)
- This makes it hard to
- Join or abut curved pieces
- Build surfaces with complex topology or structure


