

CSE 190: Virtual Reality Technologies

LECTURE #19: PANORAMA IMAGING

Upcoming Deadlines

Sunday, June 6: Project 4 due

June 7+8: Final exam Monday 11:30am – Tuesday 11:30am

App Presentations

Baily Chen

- Minecraft VR

Juan Ramirez

- Super Hot VR

Final Exam

Exam window: Monday 11:30am – Tuesday 11:30am

Exam duration: 3 hours (continuous block)

Exam type: written exam (Canvas Quiz)

Open book, open internet

No consulting of other people (local or remote)

No posting or discussing exam questions or answers

Panoramic Photos and Video

360° Photos



A.k.a. panoramic photographs, surround images, image spheres

360° photos simulate being in the shoes of a photographer and looking around to the left, right, up and down as desired as well as sometimes zooming.

Popular example: Google Streetview

- <https://www.google.com/streetview/>



VR Video Formats

Fixed view 3D stereo videos are typically stored side-by-side:



360 degree 3D stereo videos are stored in over-under format:



360° Video on Youtube

Youtube VR videos can be viewed with almost any VR device:

- Google Cardboard, Daydream, Gear VR, Oculus, Playstation VR, HTC Vive

Youtube supports 360 degree videos

- uses Mercator projection
- 3D stereo in over-under format with up to 8192 x 8192 pixels resolution

Example: City tour of Rome
(monoscopic 360 degree video)



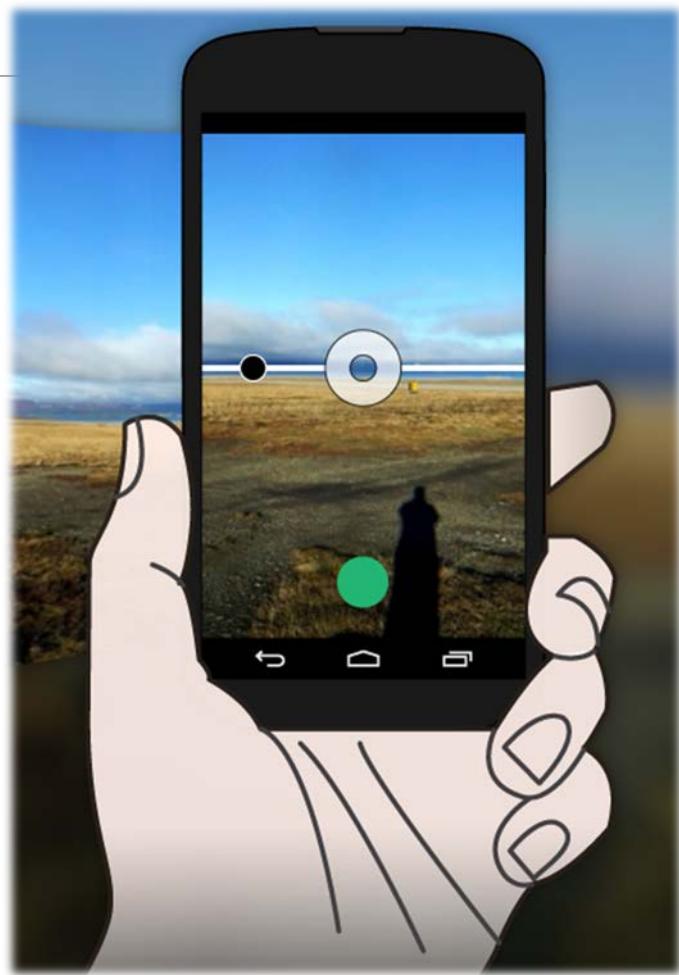
https://www.youtube.com/watch?time_continue=93&v=1ziMHIAUW0&feature=emb_logo

Panorama Capture Devices

Smartphone

Most smartphones have panorama photo capture modes/apps

Photos are 360 degrees but monoscopic



Samsung Gear 360

Two versions: released in 2016 (\$350)
and 2017 (\$230)

360° Photos:

- Dual Lens: 25.9 MP (7200 x 3600) (2016)
or 15MP (5472 x 2736) (2017)

360° Video:

- Dual Lens: up to 4096 x 2048 (24fps)

2017 version has better picture quality

Sensors:

- Gyroscope, Accelerometer

Storage: microSD

IP53 Dust and Splash-proof



V1 (2016)



V2 (2017)

Vuze XR

Photos: 6000 x 3000 pixels

Video: 5.7K@30 fps

Storage: microSD

Lenses: 2x F/2.4 210° fisheye lenses

Sensors: 2 x Sony 12MP

Price: \$400



Google VR180

Limited to 180 degree FOV

Advantage: much easier to shoot

- Camera people don't need to hide
- Camera and audio equipment can be used almost like in traditional video production



Lenovo Mirage Camera



YI Horizon VR180 Camera

Vuze+

Spherical Resolution: 4K (per eye)

Frame rate: 30fps for 3D or 60fps for 2D

Sensors: 8 Sony FHD image sensors

Lenses: 8x F/2.4 fisheye lenses

Media FOV: 360°x180° (Full Spherical)

Price: \$700



Nokia Ozo

Released 2015

Discontinued 2017

Price: \$45,000

8 lenses

3D 360 degree stitching



Samsung 360 Round

Price: \$10,500

17 cameras with 2MP image sensor and F1.8 Lens

- 16 horizontal, 1 up camera

3D Video 3D: 4096 x 2048 at 30fps per eye

6 microphones for spatial audio

IP65 Splash and Dust Resistant

Weight: 4.3 lbs



3D Video: Google Jump Yi Halo

Price: \$20,000

16 horizontal cameras + 1 up camera

Sensors: Sony IMX377, 1/2.3", 12 megapixels CMOS

Lenses: F2.8 aperture / 155° wide-angle

Omni-directional microphone

Battery: ATL 93Wh high density lithium polymer battery, battery life 100 minutes in video recording

Video and photo resolution:

- 8192x8192 @30fps



CAVECam

For full 360° by 180° Panoramas

By UCSD's Drs. Tom DeFanti and Dan Sandin

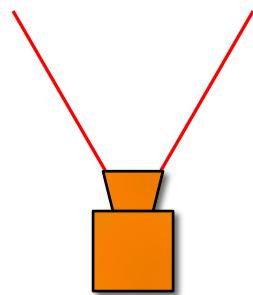


Panorama Capturing

Panorama v Stereo Movie v Stereo Panorama

Panorama

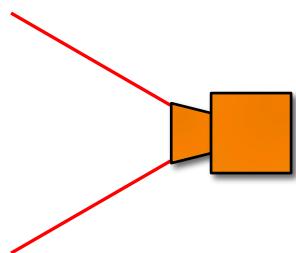
mono & head rotation



Panorama v Stereo Movie v Stereo Panorama

Panorama

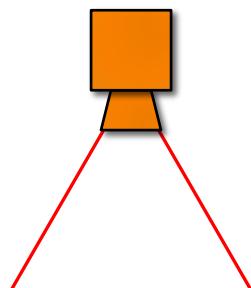
mono & head rotation



Panorama v Stereo Movie v Stereo Panorama

Panorama

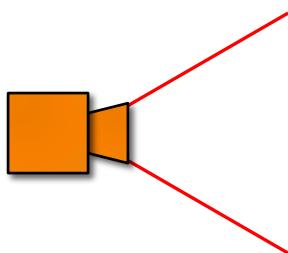
mono & head rotation



Panorama v Stereo Movie v Stereo Panorama

Panorama

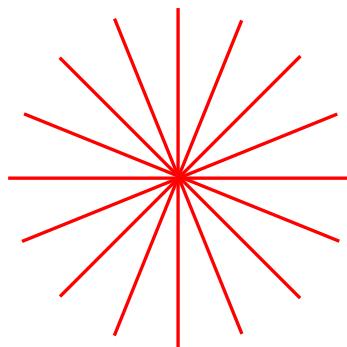
mono & head rotation



Panorama v Stereo Movie v Stereo Panorama

Panorama

mono & head rotation

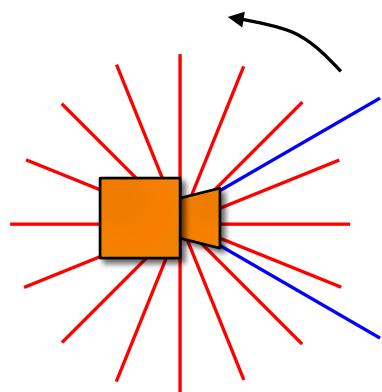


1 center of
projection!

Panorama v Stereo Movie v Stereo Panorama

Panorama

mono & head rotation

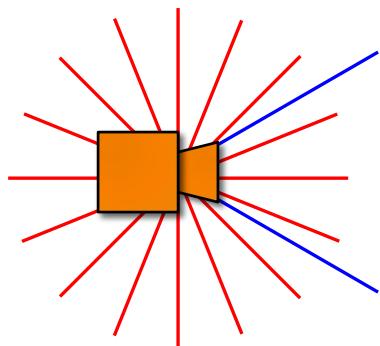


1 center of
projection!

Panorama v Stereo Movie v Stereo Panorama

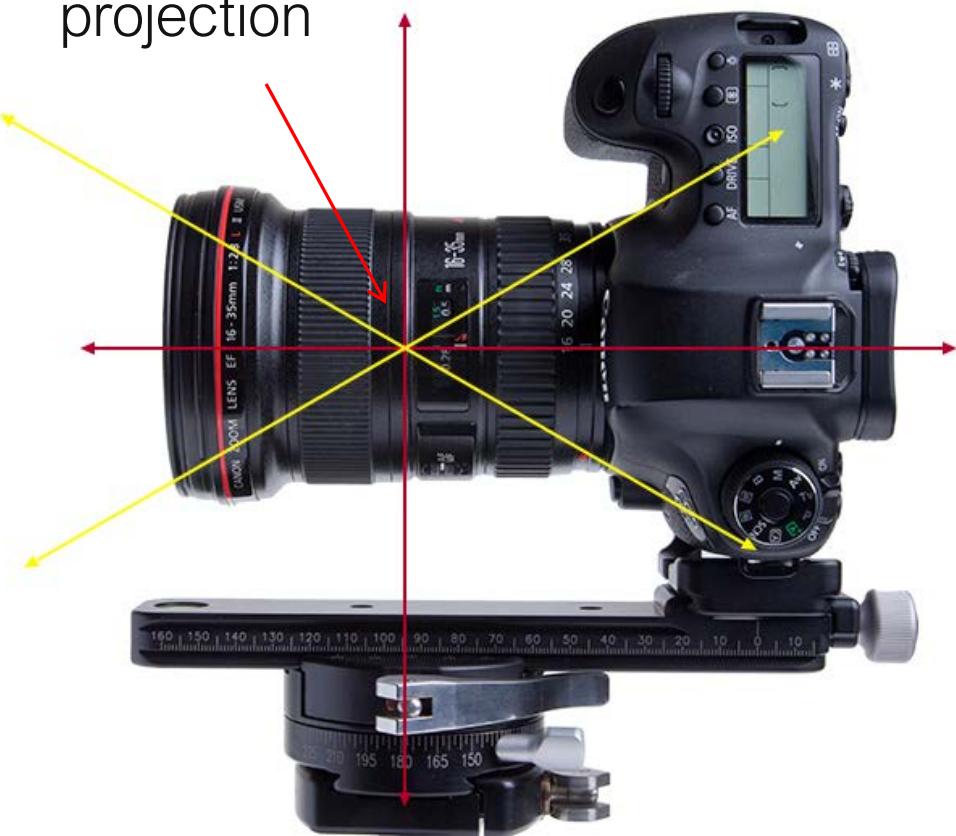
Panorama

mono & head rotation



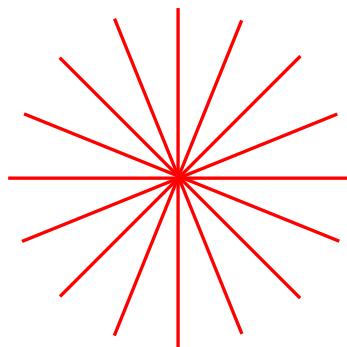
1 center of
projection!

center of
projection



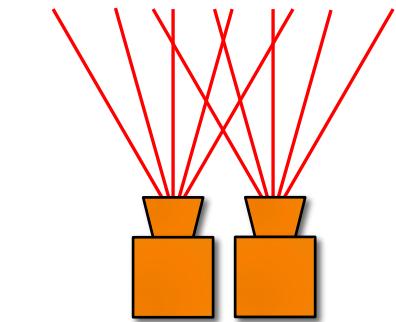
Panorama v Stereo Movie v Stereo Panorama

Panorama



1 center of
projection!

Stereo

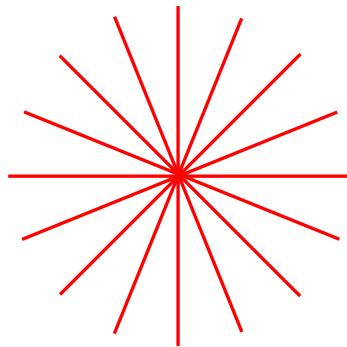


Stereo Panorama

stereo & head rotation

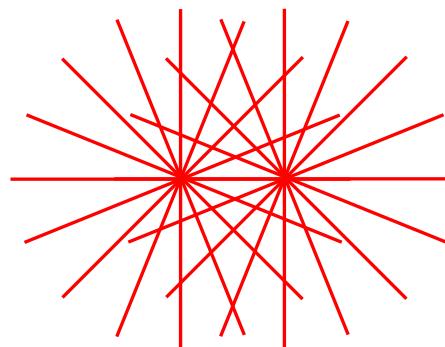
Panorama v Stereo Movie v Stereo Panorama

Panorama



1 center of
projection!

Stereo



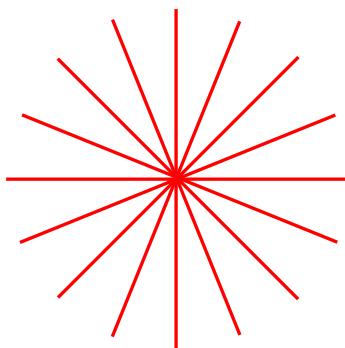
2 centers of
projection!

Stereo Panorama

stereo & head rotation

Panorama v Stereo Movie v Stereo Panorama

Panorama



1 center of
projection!

Stereo

stereo & no head rotation



2 centers of
projection!

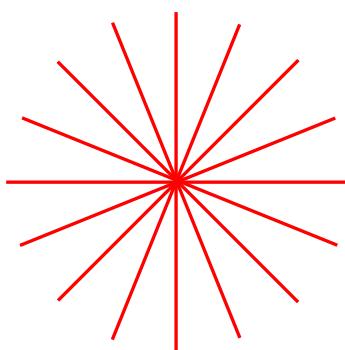
Stereo Panorama

stereo & head rotation



Panorama v Stereo Movie v Stereo Panorama

Panorama



1 center of
projection!

Stereo

stereo & no head rotation



2 centers of
projection!

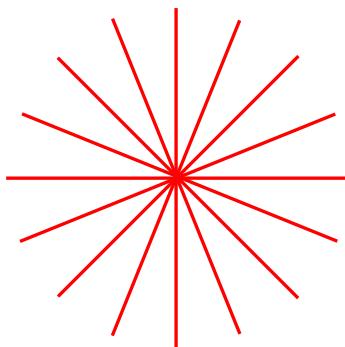
Stereo Panorama

stereo & head rotation



Panorama v Stereo Movie v Stereo Panorama

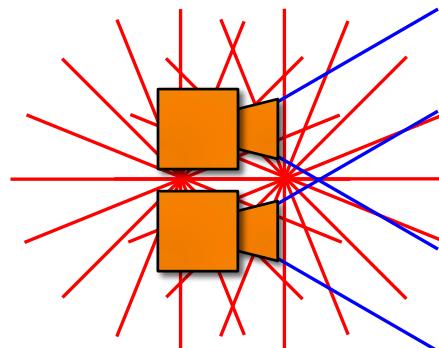
Panorama



1 center of
projection!

Stereo

stereo & no head rotation



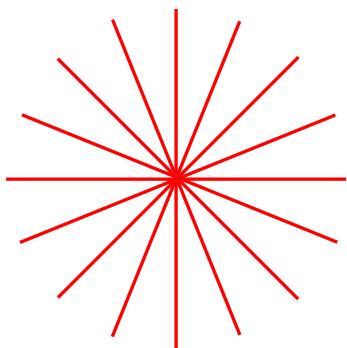
2 centers of
projection!

Stereo Panorama

stereo & head rotation

Panorama v Stereo Movie v Stereo Panorama

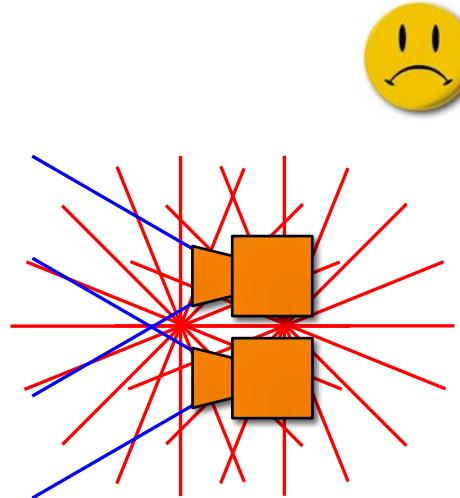
Panorama



1 center of
projection!

Stereo

stereo & no head rotation



2 centers of
projection!

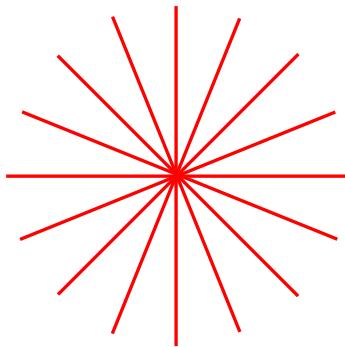
Stereo Panorama

stereo & head rotation



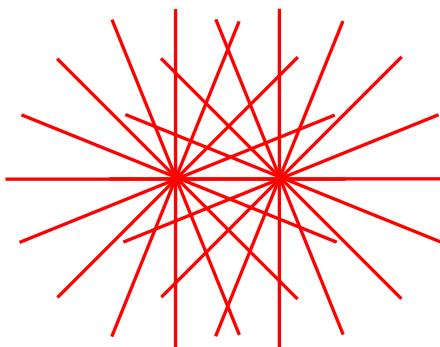
Panorama v Stereo Movie v Stereo Panorama

Panorama



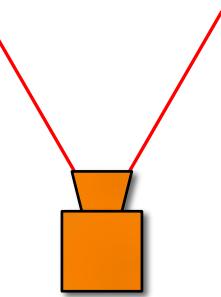
1 center of
projection!

Stereo



2 centers of
projection!

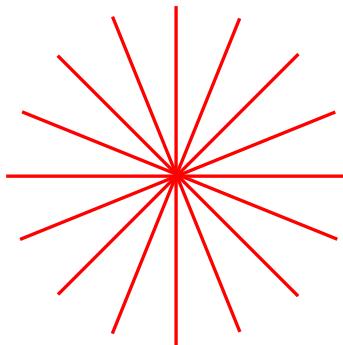
Stereo Panorama



stereo & head rotation

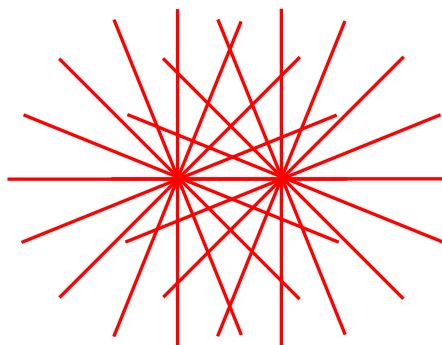
Panorama v Stereo Movie v Stereo Panorama

Panorama



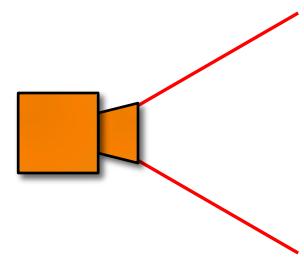
1 center of
projection!

Stereo



2 centers of
projection!

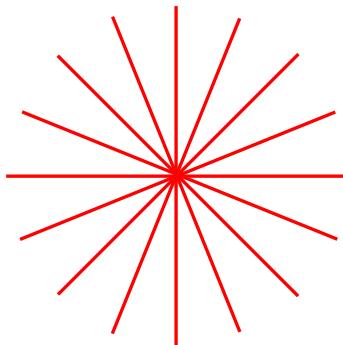
Stereo Panorama



stereo & head rotation

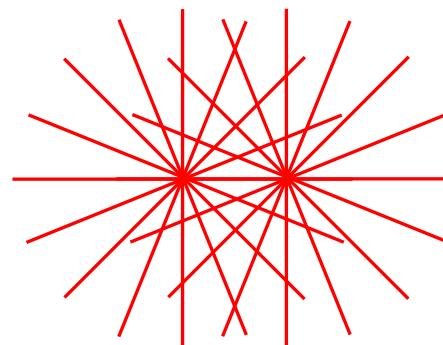
Panorama v Stereo Movie v Stereo Panorama

Panorama



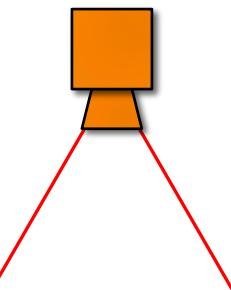
1 center of
projection!

Stereo



2 centers of
projection!

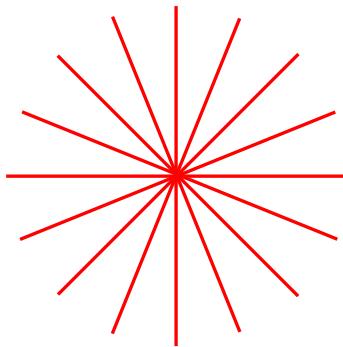
Stereo Panorama



stereo & head rotation

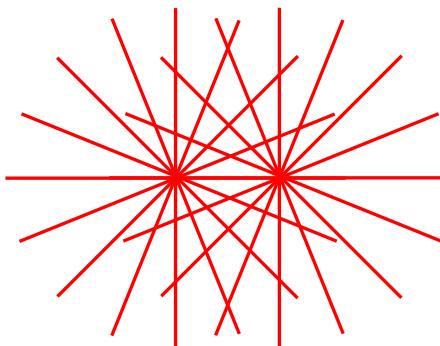
Panorama v Stereo Movie v Stereo Panorama

Panorama



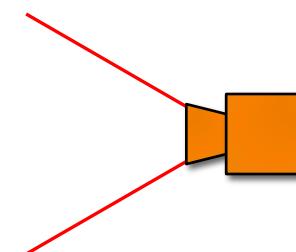
1 center of
projection!

Stereo



2 centers of
projection!

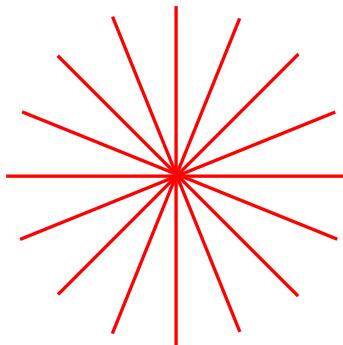
Stereo Panorama



stereo & head rotation

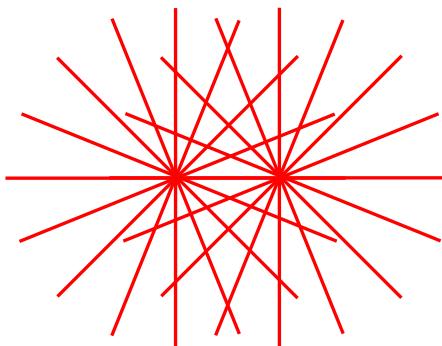
Panorama v Stereo Movie v Stereo Panorama

Panorama



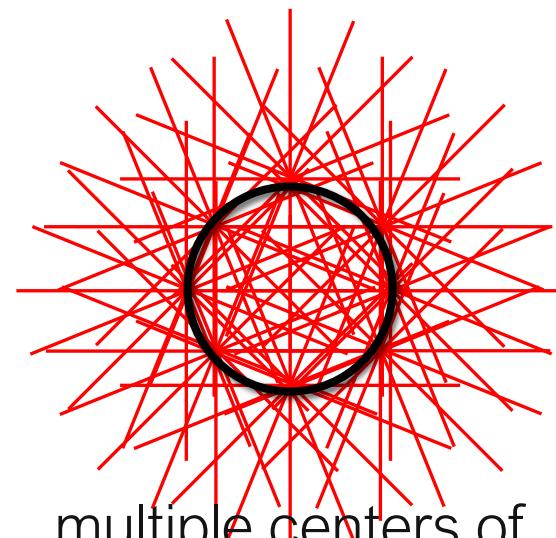
1 center of
projection!

Stereo



2 centers of
projection!

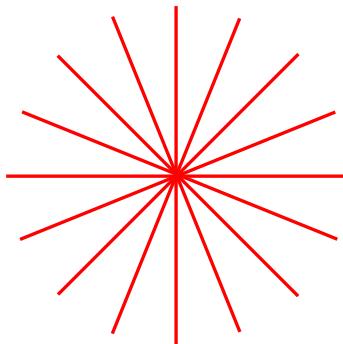
Stereo Panorama



multiple centers of
projection

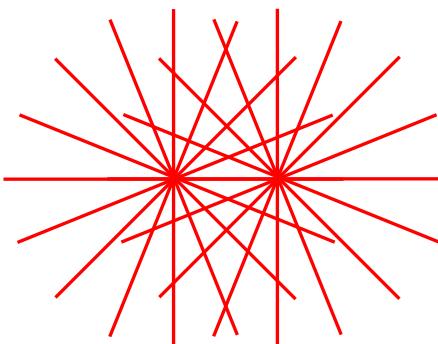
Panorama v Stereo Movie v Stereo Panorama

Panorama



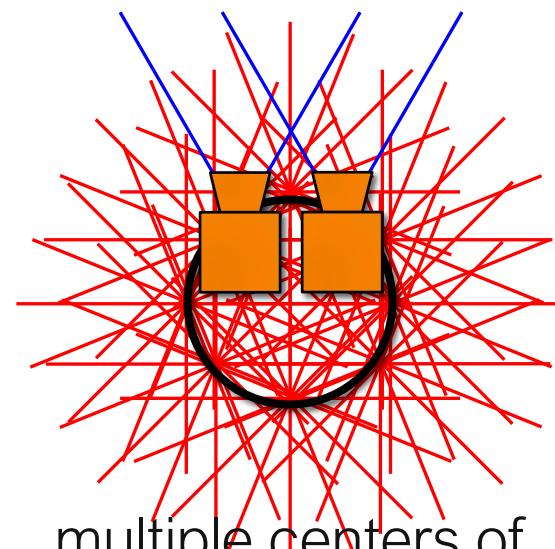
1 center of
projection!

Stereo



2 centers of
projection!

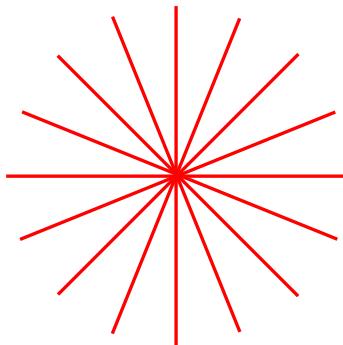
Stereo Panorama



multiple centers of
projection

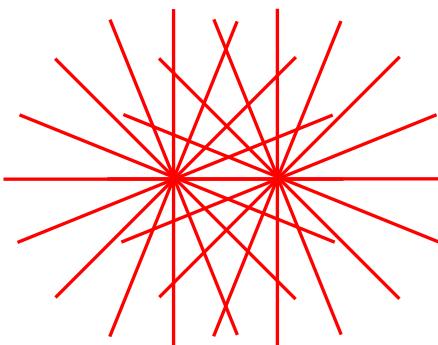
Panorama v Stereo Movie v Stereo Panorama

Panorama



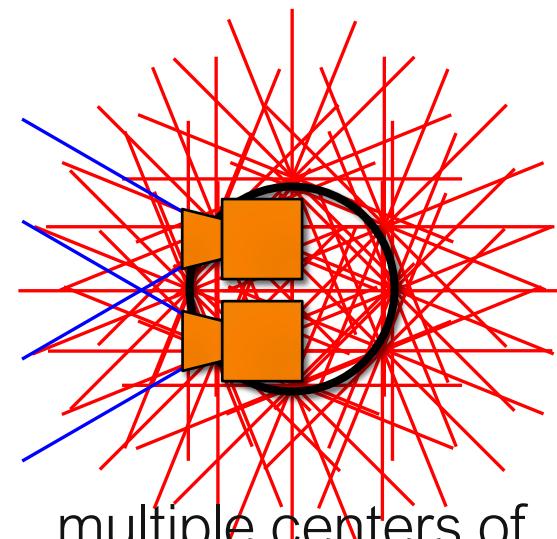
1 center of
projection!

Stereo



2 centers of
projection!

Stereo Panorama



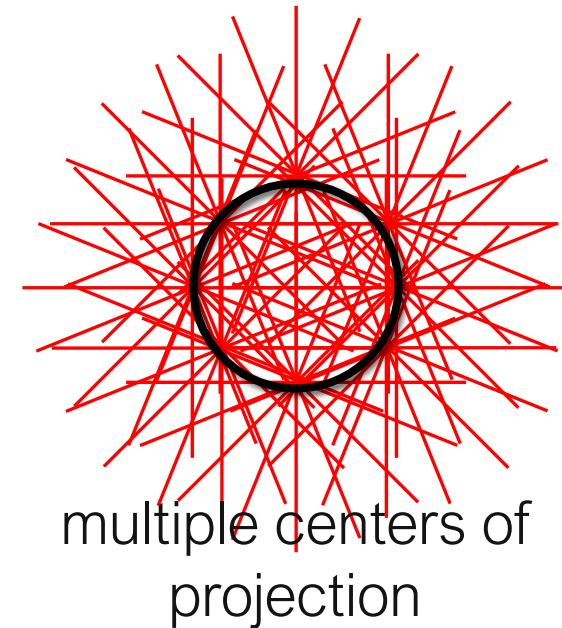
multiple centers of
projection

Panorama v Stereo Movie v Stereo Panorama



Light Field!

Stereo Panorama
stereo & head rotation



multiple centers of
projection

Panorama v Stereo Movie v Stereo Panorama

Panorama

mono & head rotation



Stereo

stereo & no head rotation



Stereo Panorama

stereo & head rotation



horizontal-only
parallax

Stitching

Panoramas

Slides from Marc Levoy's excellent CS 178 course

Stitching images together to make a mosaic



Panoramas

Slides from Marc Levoy's excellent CS 178 course

What kind of transformation do we need?



translation?



rotation?



perspective!

Panoramas

Slides from Marc Levoy's excellent CS 178 course

Stitching images together to make a mosaic



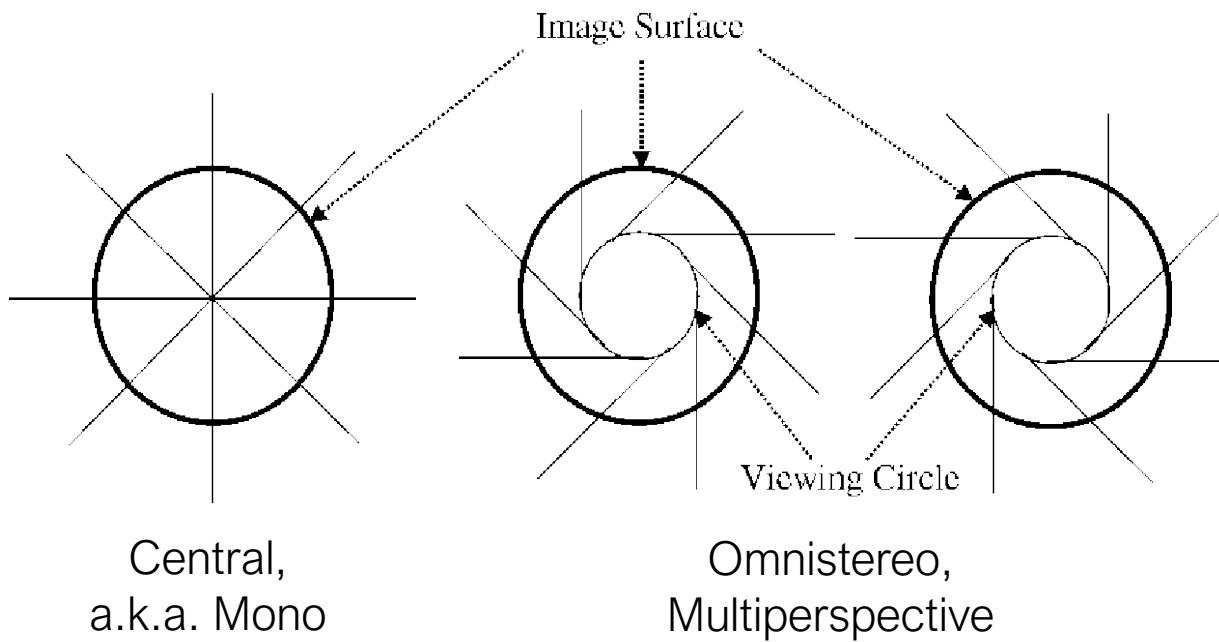
- ◆ step 1: find corresponding features in a pair of images
- ◆ step 2: compute perspective from 2nd to 1st image
- ◆ step 3: warp 2nd image so it overlays 1st image
- ◆ step 4: blend images where they overlap one another
- ◆ repeat for 3rd image and mosaic of first two, etc.

Omnistereo

Omnistereo

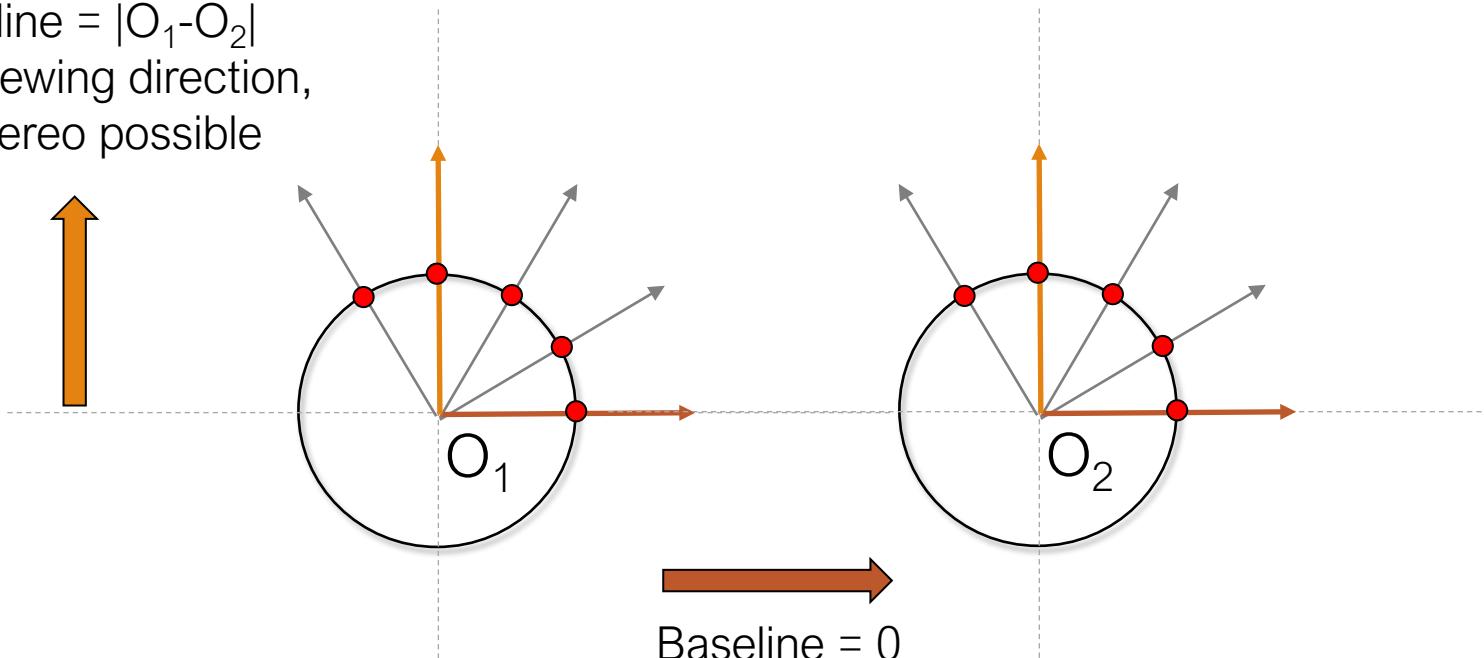
Can we display a 360 degree stereo panorama image in a surround screen virtual environment such as a CAVE so that multiple users can see a correct 3D image in all directions, without head tracking?

Comparison: Mono and Stereo Panoramas



A Pair of Mono Panoramas

Baseline = $|O_1 - O_2|$
in this viewing direction,
i.e., stereo possible



Baseline = 0
in this viewing direction,
i.e., no stereo

Head Rotation

slide by Hari Lakshman (EE 368)

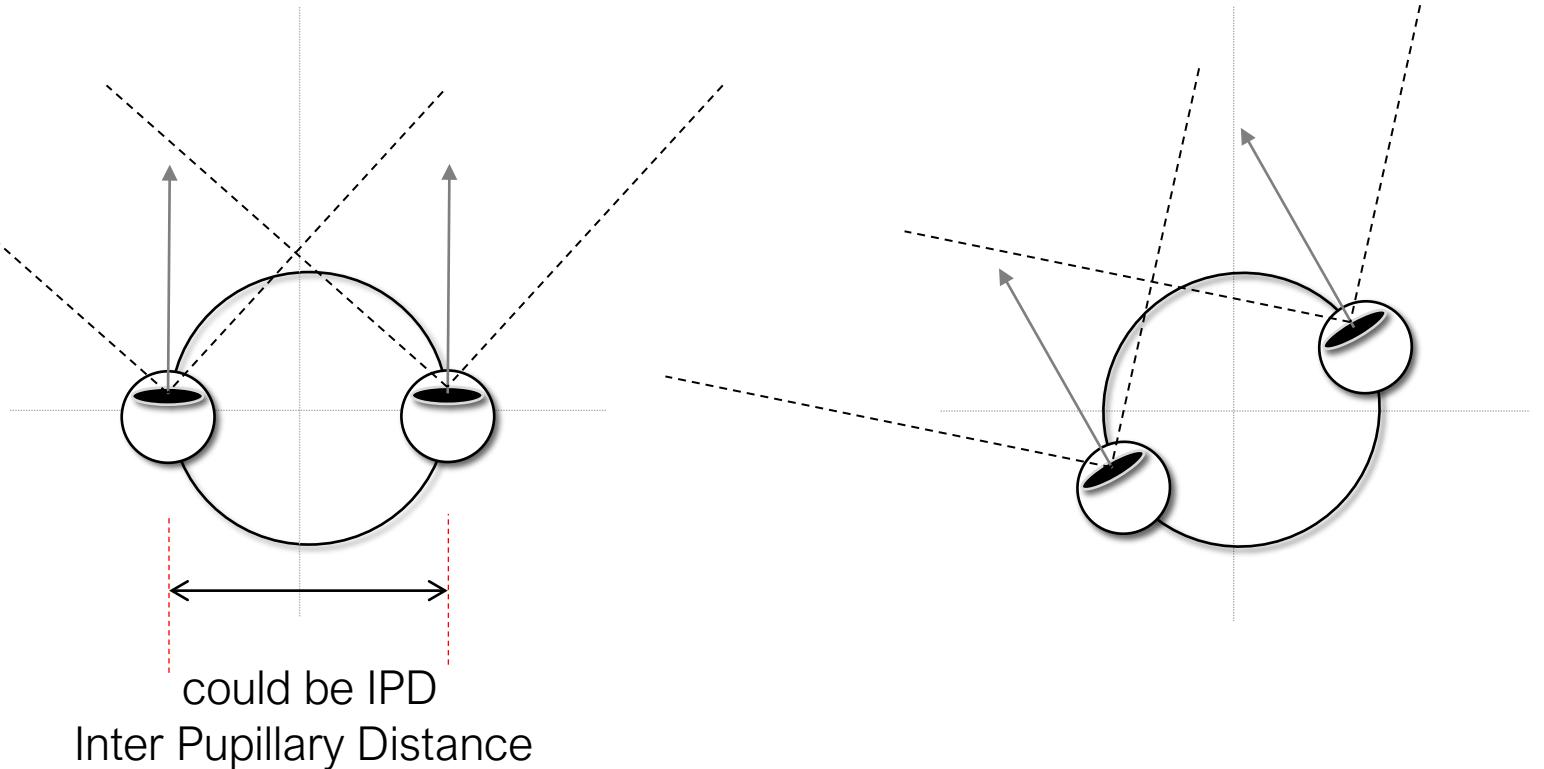
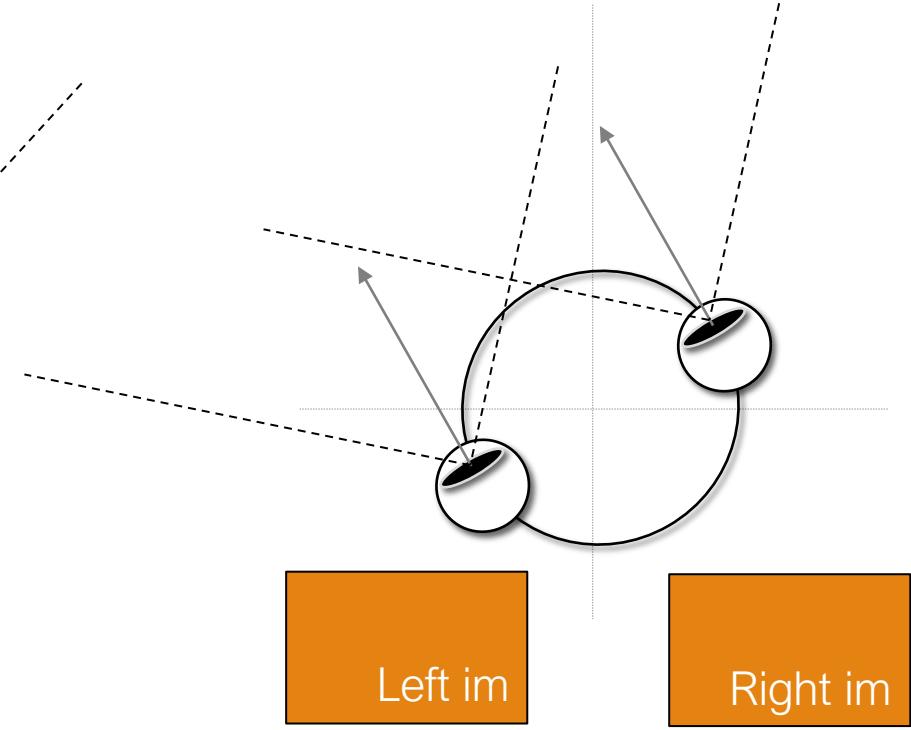
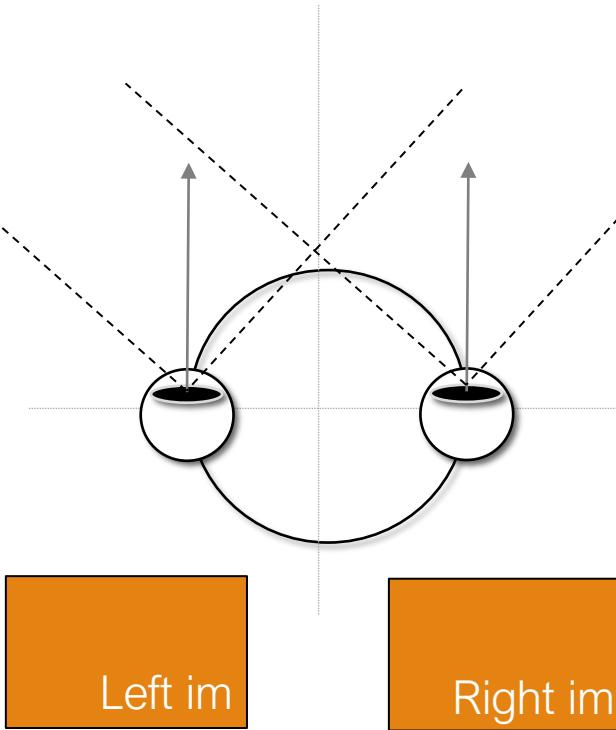


Image Pair for Each Direction

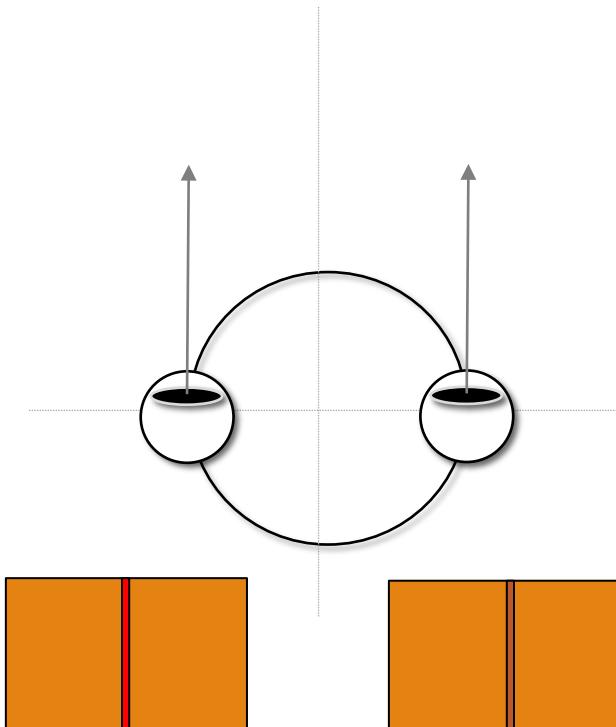
slide by Hari Lakshman (EE 368)



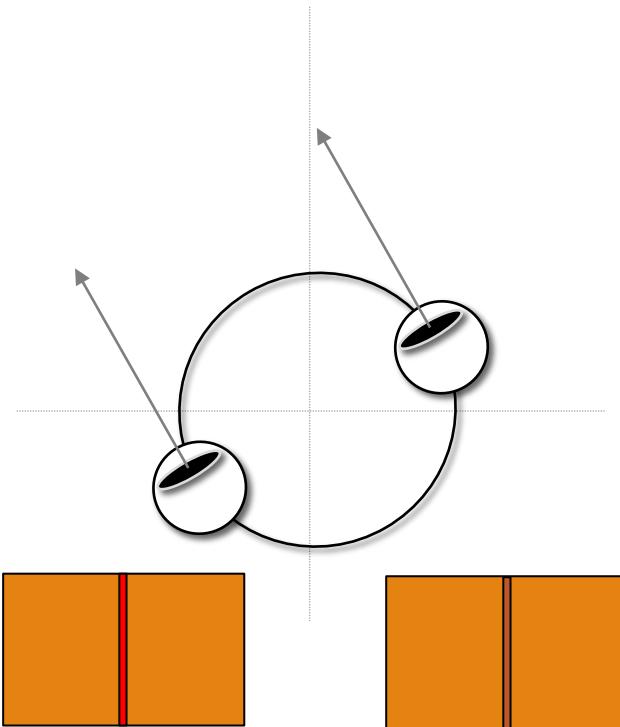
Store image pair for each direction → Problem: Too much data

Approximation: Store only Middle Ray

side by Hari Lakshman (EE 368)

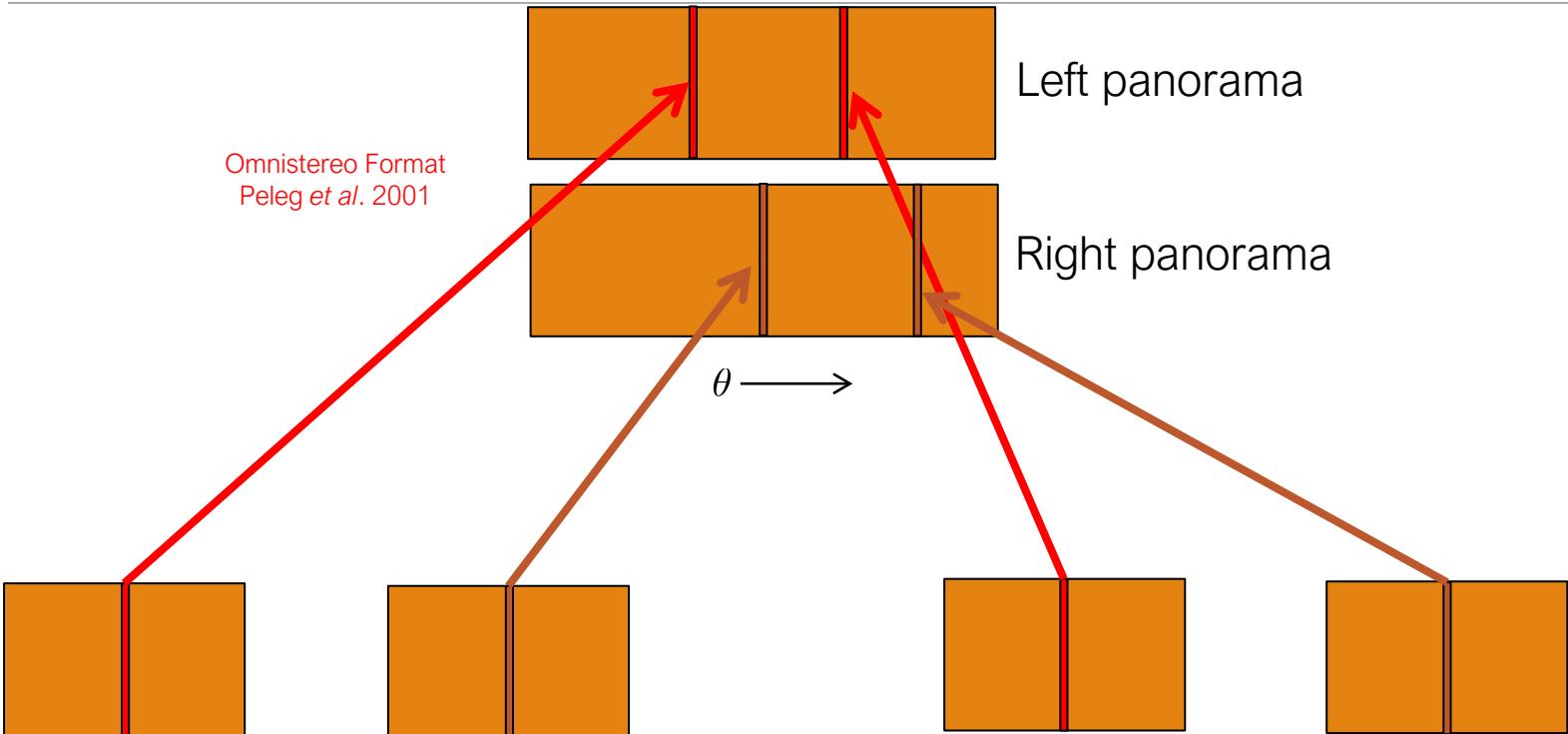


Omnistereo Format
Peleg *et al.* 2001

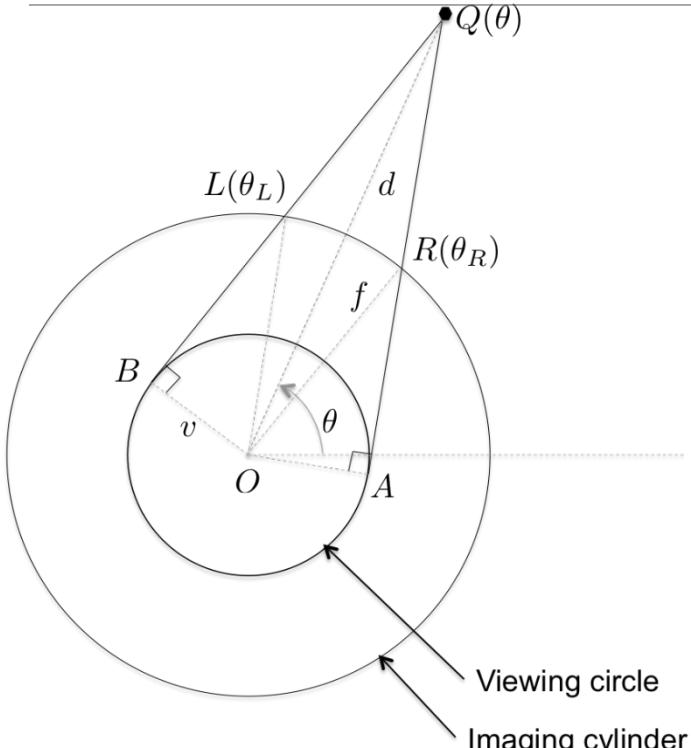


Approximation: store only middle ray for L and R eyes for each direction

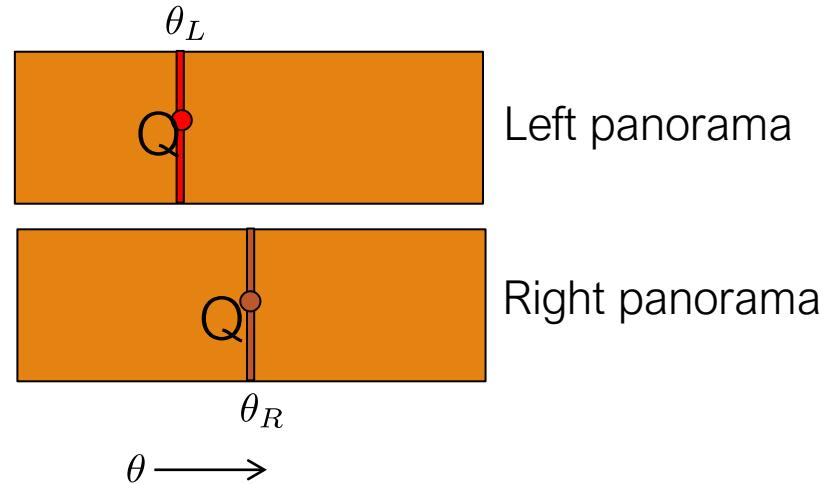
Omnistereo Panoramas



Omnistereo: Geometry Details



Q: scene point
d: distance to Q from origin
v: viewing circle radius
f: imaging cylinder radius
L, R: coordinates of Q in panoramas

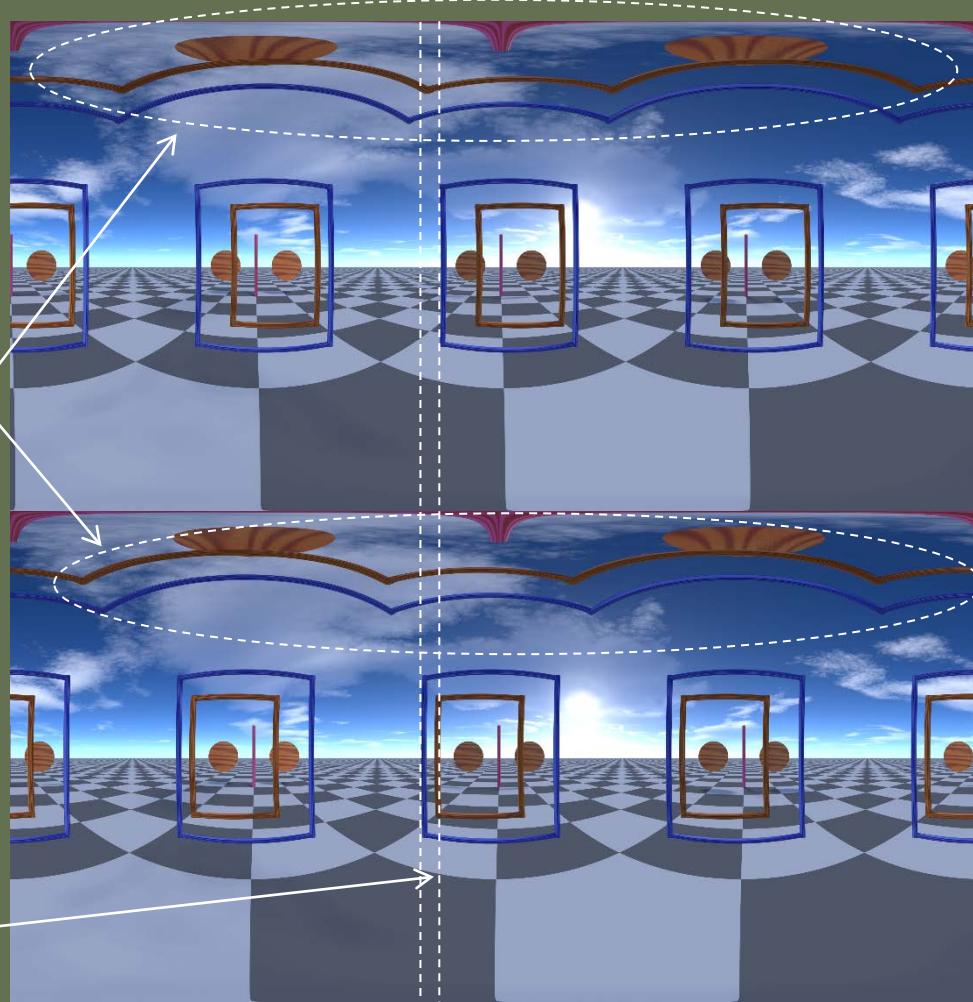


Omnistereo example

side by Hari Lakshman (EE 368)

Sphere-to-plane
distortions

Disparity



Left panorama

Right panorama