



CSE 167 DISCUSSION 5

OCTOBER 31, 2018





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Announcements



- Happy Halloween!
- Project 3 due this Friday 11/02
- Feel free to get some candies before you leave



Overview



- View frustum culling
- A little Scene Graph
- Some most asked questions (if we still have time)





- It's possible to do frustum culling in different spaces:
 - View space (Camera space)
 - World space
 - NDC space (Canonical volume space)





- It's possible to do frustum culling in different spaces:
 - View space (Camera space)
 - Do culling after applying view matrix
 - We only need to calculate the plane representation once





- It's possible to do frustum culling in different spaces:
 - World space
 - Do culling after applying model matrix (when we have world space coordinates)
 - We need to re-calculate the plane representation each time we move the camera.





- It's possible to do frustum culling in different spaces:
 - NDC space (Canonical volume space)
 - Plane representation is trivial
 - Note: In NDC space, view frustum is simply a [2x2x2] cube.
 - But bounding sphere is no longer a "sphere" (skewed), we would need to re-calculate the radius of it.





- Why this one?
- How it works?





- Why this one?
 - Easiest
 - Less expensive (than in NDC space)

(I may go over culling in other space EC briefly if we have enough time)







- How it works?
 - Recap: To do culling, we actually want to calculate point-to-plane distance.
 - $lack dist(x) = (x-p) \cdot n$, s.t. x is the point, p is a point on the plane, n is plane normal
 - When dist(x) > 0, the point x is on the side of the plane the normal points to.





How it works?

$$dist(x) = (x - p) \cdot n$$

- Recap: To do culling, we actually want to calculate point-to-plane distance.
- Therefore, we need following information in camera space:
 - Point coordinate
 - A point on each plane
 - Plane normal of each plane





- How it works?
 - o Recap: Camera space coordinate
 - $oxed{\circ}$ Transform a point p to camera space: $p'=C^{-1}Mp$
 - glm::vec3 new_p = Window::V * toWorld * old_p;







- How it works?
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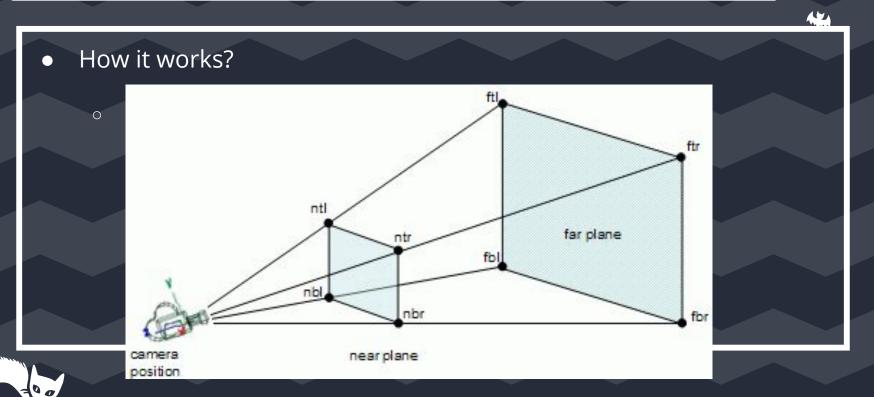




- How it works?
 - A point on each plane:
 - We want the 8 corners of view frustum
 - We only need to calculate two points (Chalkboard time).
 - The rest can be done by symmetry.









- How it works?
 - Recap: Camera space coordinate
 - +y axis: normalize(cam_up)
 - +z axis: -cam_forward = -normalize(cam_lookat cam_pos)
 - +x axis: normalize(cross(cam_up,+z axis))
 - Recall: Window::P = glm::perspective(fovy, aspect, near, far);





- How it works?
 - A point on each plane:
 - We want the 8 corners of view frustum
 - We only need to calculate two points.

$$\begin{array}{l} \bullet \quad \mathsf{Ex.} \quad ntl = (-near \cdot tan(\frac{fovx}{2}), near \cdot tan(\frac{fovy}{2}), -near) \\ = (-aspect \cdot height, near \cdot tan(\frac{fovy}{2}), -near) \end{array}$$

■ The rest can be done by symmetry.







- How it works?
 - Recap: To do culling, we actually want to calculate point-to-plane distance.
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- How it works?
 - Plane normal of each plane:
 - We just calculated the points on each plane.
 - Assume P_lt, P_rt, P_lb, P_rb are four corners of a plane (Chalkboard time)





- How it works?
 - \circ Back to point-to-plane distance formula, $\ dist(x) = (x-p) \cdot n$
 - Pseudocode:





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How it works?

```
dist(x) = \overline{(x-p)\cdot n}
```





 $dist(x) = (x - p) \cdot n$

• How it works?



Scene Graph



- Need to maintain a tree of nodes for the android army
 - Can be iterated through by calling draw() on the root
 - It recursively calls draw() on the rest of the tree
- Transform is only responsible for transformation, while Geometry is only responsible for render.



Scene Graph



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- Simply add transformations to animate your androids
 - All modifications to Transform should be in idle_callback().
 - (You don't have to do this, but it makes your code cleaner)
- You should not have multiple copies of vertices in memory for the same geometry.
 - o Don't do this: having 3 * 6909 * 50000 glm::vec3 in memory for body, just

because you want to render 50000 robots



Texture/Change in OBJ files



- Make sure to parse as:
 - f v1/vt1/vn1 v2/vt2/vn2 v3/vt3/vn3
- And realign so that we can use a single std::vector of indices
- Make sure to use std::vector<glm::vec3> for positions/normals and std::vector<glm::vec2> for texture coordinates
 - For HW2 we could use std::vector<float> for positions/normals, since the memory layout is the same as std::vector<glm::vec3>



Extra Credit



- Debug Mode
- Hierarchical Culling



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